# I-59 DESIGN OF MARINE STRUCTURES PROVIDED WITH RUBBER FENDERS CONSIDERING SHIP LOAD IMPACT

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### Introduction

In the annual conference of JSCE held in Osaka in November 1970, the authors presented, (Abstract \_ -174), a hypothetical method for designing berthing structures provided with fenders of linear or non-linear spring constants.

The method of analysis is based on the dynamic behaviour of the system (ship, fender structure) after collision.

This paper describes the practical application of the method on structures provided with rubber fenders, which are in this class, are being used extensively due to their large energy-absorbing characterstics.

## Existing Methods For Design Rubber Fenders System

Engineers involved in designing berthing structure, estimate, first, the part of the ship's kinetic energy that transferred to the fender system(fender and struct.) by using emperical formaulas. Second, the fender is selected to absorb all the estimated energy. Third, the structure is then designed to withstand the horizontal load corresponding to the selecting fender absorbing capacity. The fender absorbing capacity, and consequently the design horizontal load, are evaluated from the

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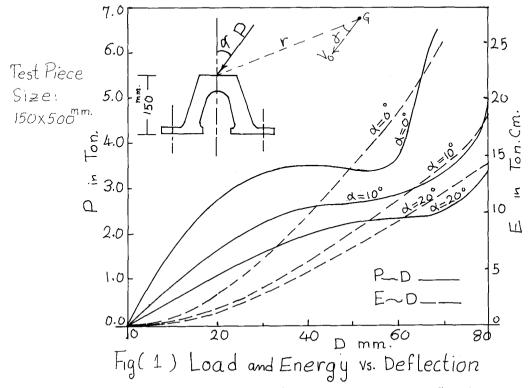
behaviour of the fender under statical tests. Thus by this procedure the dynamic action after collision is overlooked.

# The dynamic motion of the system after collision

with the following initials conditions of motion;

$$x_1 = x_2 = \theta = \phi \approx 0.0$$
  $\dot{x}_1 = \dot{\theta} \approx \dot{\phi} = 0.0$  and  $\dot{x}_2 = V_0$ 

In solving these eq. the effect of the direction of the ship's impact load should be taken into consideration as the energy absorbing capacity of rubber fenders depens on the load direction as seen by the tests result in fig.(1) carried out by the authors.



N.B. The tests are carried on rubber fenders Produced by Sumitomo Rubber Co.

# Selection of the Parameters for Solutions of the Motion Equations

On the basis of the experimental and theoretical work carried out by investigators involving in Naval Architecture, the authors could derive formulas for estimating the virtual mass of the ship in case of berthing, these are;

$$M_2$$
= virtual mass in sway motion = M + 1.38 d L  $I_{2-2}$ = virtual moment of inertia in yawing motion =0.04 L  $M_2$   $I_{1-1}$ = " " " rolling " =0.202 B M

and

 $H_{\eta}$  = vertical distance between the ship's center gravity and its metacenter

= 1.33 (B-L/
$$c_1$$
)/  $c_2$ 

$$C_1 = 12.5$$
 ( U- shape ) , 13.5 ( V-shape)  $C_2 = 5.7$ 

On the basis of investigations of existing berthes in Kobe Harbour, the effective mass of the structure  $M_1$  can be assumed ,for the first design approximation, as

$$M_1 = 0.01 M_2$$

L, d, B, and M are the ship's length, draft, beam and the displacement weight respectively. The solution of the eq. is carried in step-by-step using numerical integration methods as Newmark  $\beta$  method.

# APPLICATION

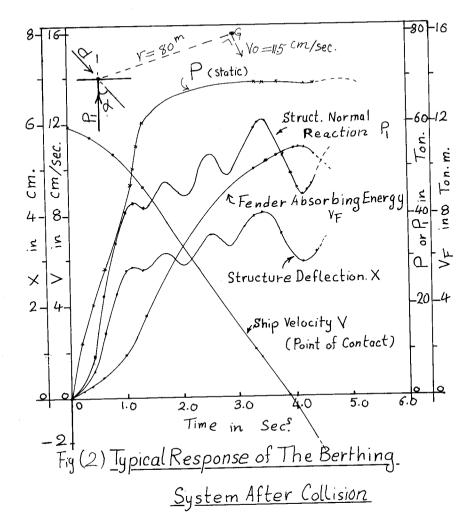
A tanker ship of 40 000 ton displacement weight is approaching to berth with velocity  $V_0$ =115 cm./sec. Assuming the berthing structure consisting of two dolphins of spring constant  $K_1$ =15 ton./cm. each .Two cases of berthing are to be investigated.

$$L= 200 \text{ m}$$
.  $d = 10.30 \text{ m}$ .  $B = 25.80 \text{ m}$ .

- I ) Broadside Berthing
- II) Oblique Berthing

$$r = 80.0 \text{ m.}$$
  $H = 3.00 \text{ m.}$ 

Case Nº	Description of the Fender		Max. Dynamic Load	Max. Deflec. of Structure.	Notations
I	Each dolphin is Provided with one	Per Dolphin 20.5	Per Dolphin	In Load direction	
工	Peice of <b>V600</b> Hx2501 Produced by Tokyo Rubber Dock Fender		79.62 <sup>ton</sup>	5.31 cm	8-90 <sub>VV</sub>



[ Case II Oblique Berthing]

# CONCLUSIONS

By the design procedure presented here above ,the part of energy that transfered during berthing to each of the fender and the structure and the max. impact force can be evaluated. Economic design can be achieved by trying different types of structures ( different  $K_1$  ) and in each trial , the structure is provided with different types of fenders ( different  $P \sim D$  ) untill the allowable deflection of the structure accompanied by the min. max.dynamic force is attained.