論說報告

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THEORY OF INFLUENCE EQUATIONS.

By Tadafumi Mikuriya, Assoc. Member.

Synopsis.

In 1932 the writer presented in a very brief way the Theory of Influence Equations in this journal under the title of "The Derivation of Influence Equations of Statically Indeterminate Structures." Since that presentation of the principle was rather too general to insure a complete understanding of it and its practical value in application to curved structures. In the following pages the writer wishes to present the matter more in detail in order to clear any doubt about this theory and to illustrate with specific examples the degree of accuracy with which the principle can be applied.

INTRODUCTION.

Before going into the discussion the writer wants to express his appreciation for the sincere and inspiring discussion and comments made by Mr. Makizi Shono.

The main emphasis of the Influence Equation Theory lies in the close harmony between it and its practical application in the solution to statically indeterminate structures within a reasonable limit. The usefulness of the Influence Equation Theory depends upon its flexibility in practical use, its high degree of accuracy, and the ease with which it can be applied to the solution of practical problems.

As an illustration of the accuracy of the principle the writer took the same fixed arch which was built at the Experimental Station at the University of Illinois and on which a series of tests were made recently by Prof. W. M. Wilson who kindly contributed the experimental data to the writer.

Here the writer would like to express his deep appreciation for the Prof. Wilson's cooperation.

For the other illustration the writer took the ring which was also built at the Experimental Station at the University of Illinois and upon which a series of tests were made in 1908 by Prof. Talbot. The experimental results are given in bulletin No. 22 published by the same institution in 1908.

The writer has solved the problem of these structures with his Influence Equation Theory and made tables and diagrams which check with results obtained by experimental and theoretical methods. These tables and diagrams show the accuracy of the theory and prove conclusively that there is no danger in the application of this principle to practical problems.

DATA.

In the test a concentrated load, 2000 lbs., was applied at point 10, 12, 14 and 16 of a reinforced concrete fixed arch whose properties are given in Fig. 1 and Table 1. Modulus of elasticity of steel and concrete are as follows:

Steel $E_s = 29\ 000\ 000\ 1$ bs. per sq. in. Concrete $E_c = 3\ 300\ 000\ 1$ bs. per sq. in.

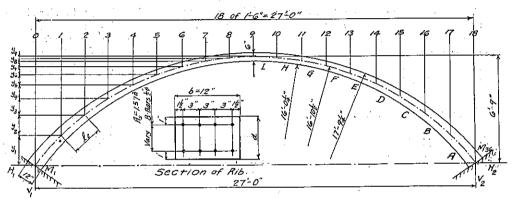


Fig. 1

APPLICATION OF THEORY.

Before going into the computation let it be understood that the arch was divided into 18 equal parts as shown in Fig. 1.

As was explained and illustrated in the writer's previous article published in the journal September 1932 that

first of all it is necessary to establish Influence Equation by inspection as shown in **Table 2.** For establishing the equations it is necessary to refer to **Table 5** and **6** in the September 1932 journal.

	x	y	l	d	Ь	(n-1) A5	Average I	<u>L</u>
7	18"	20.873	27.562	11.119"		0	1831.98	A=.015045
2	÷	16.152	24.185	10.346		8 5	1475.87	B=.016386
3	"	12.770	22.070	9.640		1 2	1198.31	C=.0/8417
4	4	10.106	20,643	8.980		2 5	973,97	D=.021215
5	"	7.8.66	19.644	8.352	,,	8 8	789.76	E=,024872
6	',	5,900	18.942	7.747	`	10 %	636.14	F=,029776
7	`	4.106	18.462	7.158	l	3 6	507.18	9 = 036400
8		2,425	18.162	6.576		1 1	398.36	H =,045588
9	*	0.802	18.018	6,000		1 12	306.75	1=,058738

In Table 2 we have 21 un-

knowns and 21 conditional equations. It looks like a quite laborious piece of work to solve 21 simultaneous equations. However this number can be reduced to 3 equations for 3 unknowns at the left end, M_1 , H_1 and V_1 .

Replace the coefficients of moments by X, Y and Z terms as shown in **Table 3** then proceed the operation of elimination as shown in equations (22) to (39) for X and the same for Y and Z. Then sum up equation (22) to (39) and subtract equation

(1) for X and repeat for Y and Z then we have 3 equations as shown in **Table 4**. Equations (40), (41) and (42) are the Influence Equations for the left and unknowns M_1 , H_1 and V_1 . These 3 equations can be written by inspection for any

Table 2

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Table 3

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number of segments made.

In this numerical example, first of all, we have to obtain the individual value of ϕ , θ , X, Y and Z. The values of ϕ and θ will be determined by general equations given in September 1932 journal.

$$\begin{array}{ll} \phi_{(2n-1)} = 3\sum_{1}^{(n-1)}y \pm y_n & \phi_{2n} = 3\sum_{1}^{(n-1)}y \pm 2y_n \\ \theta_{(2n-1)} = 3\sum_{1}^{(n-1)}x \pm x_n & \theta_{2n} = 3\sum_{1}^{(n-1)}x \pm 2x_n \end{array}$$

After finding the values of ϕ and θ determine the individual values of X, Y and Z referring to Table 2 and 3.

All values of ϕ , θ , X, Y and Z are given in **Table 5** and **6** for this numerical example.

Table 5

_			
	φ	θ	N
T	y, = 20,873	0, = Z	019 = 28%
2	29, = 41.746	Oz = 2%	820 = 29X
3	35,+5 ₂ = 78.77/	03 = 4X	8 = 3/2
4	34,+242 = 94.923	Og = 5%	022= 32X
5	32,74+43= 123.845	B ₅ = 7×	023= 34X
6	35,29+293=/36.615	0 = 8x	Bz = 35%
7	35,3+9+= 159.491	B = 10%	025 = 37Z
8	35,39+24,= 169.587	8 = 11x	Ba6 = 38%
9	32†J+J5 = 187.569	$\theta_g = 13x$	827=40X
10	3Σ ⁴ y+2y ₅ = /95435	8,0 = 14x	0=8 = 4/X
<u>//·</u>	35,9+y = 209.201	A., = 16x	Az4 = 43X
12	3254+241=215.101	A,z = 17%	030 = 44X
/3	31,444, = 225.107	8,3 = 192	031 = 462
14	32°4+24, = 229.2/3	014 = 20X	B32 = 47X
15	32,4t Jp = 235 744	Bis = 22X	033 = 49X
16	3274+248= 238.169	B16 = 23X	A34 = 50%.
17	32,9+49 = 241.396	$\theta_{ij} = 25Z$	835 = 52X
18	32,4+24, 242.198	018 = 26X	036 = 53Z

Table 6

_			
L	X	· Y	z
a	.015045	. 3/4034	.797385
6	.03/43/	1.918811	1.601640
٤	.034803	3.836261	1.668513
d	.039632	5,899639	1.780642
e	.046087	8.263216	1.931997
5	.054648	11.090028	2.126368
9	.066176	14.598742	2.3757/2
ħ	.081988	19.090450	2.696416
į,	.104326	25.03/69/	3.116630
Ì	.117476	28.452452	3.171852
K	.104326	25.03/69/	2.5/6974
	.081988	19.090450	1.730936
m	.066176	14.598742	1.197792
π	:054648	11.090028	824624
0	.046087	8.263216	.55670/
p	.039632	5.899639	.359486
8	.034803	3836261	.210849
χυ	.03/43/	1.918811	.095634
5	.015045	.314034	.015045
			•

For purposes of simplification we can divide equations (40), (41) and (42) by x=18" before or after the substitution of numerical values into those equations.

Now we substitute the numerical values into equations (40), (41) and (42) then we have 3 equations as shown in (1), (2) and (3) in **Table 7** Solving these 3 equations

we have influence values of M_1 , H_1 and V_1 .

Table	7

	1/2	4/	1/	Arch Short.		at point	F . 70 .	1
	M,	H	V,	6EDH/X	10	12	14	16
1	.0592082	3.862007	9.591732		1.309987	652355	.263657	.06/52/
2	11.585455	826.9284	1876.8418	-/	183.07059	72.13868	20.58473	2.546879
3	1598622	104.1469	314.94427		58.05978	30.79885	13.11213	3.196410
4	1			.92443	23.97448	24.01914	15,68642	5.34275
5		/		0/4078	-1.028240	779/33	-,43522/	-133219
6				0	0.40541	0.23559	0.10708	0.02743

In this experimental example a load 2 000 lbs. was applied at point 10,12,14 and 16 therefore the influence values of those M_1 , H_1 and V_1 will be multiplied by 2 000 lbs. Let it be understood that the equations in the tables are only the left hand side of equations and that the right hand side is equal to zero which is omitted, i.e. in equation (4) **Table 7** when the load is at point 10,

$$M_1 + 23.97448 \times 2000 = 0$$

 $V_1 + 0.40541 \times 2000 = 0$

 $M_1 = 47.949^{\prime\prime \#}$

 $V_1 = -811$

 $H_1 - 1.028240 \times 2000 = 0$

 $H_1 = +2.056$

CONVENTIONAL SIGNS.

In the author's previous article his statement concerning conventional signs may have been misunderstood therefore it will be reiterated here in a different way.

The clockwise moment will be assumed as positive and it will be also assumed that all lever arms of moments measured from the force toward the right, or upward, are positive. It follows therefore that forces acting upward or toward the left should be considered as positive, in order to be consistent with the assumed direction for positive moments.

And it is always necessary to note what portion of the member is being considered and that portion under consideration must always be specified and indicated by subscripts, M_1 , M_2 , M_3 etc.

Now M_1 , H_1 and V_1 are the moment and forces at the left end of the member therefore when we consider the reactions at the left springing the signs will be reversed because of $\Sigma M=0$, $\Sigma H=0$, $\Sigma V=0$,

 $M_L = -M_1 = +47949''^{\sharp}$, $H_L = -H_1 = -2056^{\sharp}$, $V_L = -V_1 = +811^{\sharp}$

in other words M_1 is clockwise, H_1 is acting toward the right and V_1 is acting upward.

ARCH SHORTENING.

In this experiment the effect subject to temperature change was disregarded

because there was practically no change in temperature before and after load was applied. Therefore only arch shortening will be considered.

In equations (40), (41) and (42) we have the term $6E\Delta_H/x$ which will answer the question of arch shortening.

$$\Delta_H = \frac{SL}{AE}$$
, $\frac{6E\Delta_H}{x} = \frac{6E}{x} \cdot \frac{SL}{AE} = \frac{6SL}{Ax} = 6nf$

Where E = Modulus of elasticity.

S = Stress.

A = Cross section area of arch rib under consideration.

L = Span.

x =Horizontal distance of each segment.

n =Number of segments, in this case 18.

f =Average unit stress.

The average unit stress will be tabulated as follows considering five different sections.

Arch Shortening effect, $M_1 = -0.92443 \times 6nf = -0.92443 \times 6 \times 18$ $\times f = -99.75f$ $H_1 = 0.014078 \times 6nf = 1.52f$ $V_1 = 0$

FINAL RESULTS.

After finding M_L , H_L and V_L the moment at any point may be obtaind by passing a section and taking the moment of the left hand side of the section.

 $M_L+V_Lx-H_Ly-M_0=0$ M_0 is the moment due to an external force acting on the left hand side of the section.

Table 8

<u> </u>	f 1/4"	Whe Lo	ad at	<u> </u>
Section.	10	12	14	16
0	12.03	8.82	4./0	0.13
4	18.30	13.46	7.34	2.21
9	24.40	18,50	10.33	3.16
14	19.56	17.00	12.58	7.96
18	13.85	13.42	11.46	10.20
Total	88.14	71.20	45,81	23,66
Aver. f.	17.60	14.25	9.17	4.73

Table 9

		100	id at	Point	
		.10	12	14	16
		47949	48038	3/3/3	10686
M,	Ar. Short.	1755	1420	917	472
	Tota/	49704"	49458"	32290"	111584
		2056	1558	870	266
Η,	Ar. Short.	26	2/	14	7
	Total	2082 #	1579 #	884#	273 4
V_i	·	811 #	471#	214'#	54 #

Table 10

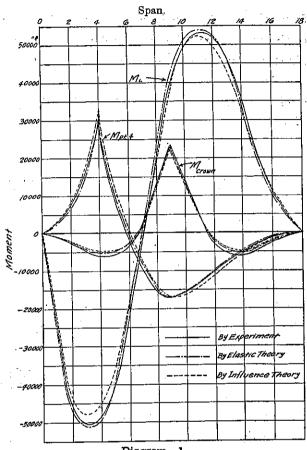
_	Experiment	LC	ad at	point		When half
	100%	10	. /2	14	16	Arch Loods
	Experi4	49596"4	52233"*	35205 "A	10915"#	147949"
10	Elastic Theo.	51022	52400	33216	10322	146960
M_L	Diff. in %	3,0	0.4	-51	- <i>5,5</i>	-0.7
	Inf. EL. The.	49704	49458	32290	11158	142610
	Diff.in %	0.4	-5.2	-8.2	1.0	-3.6
	Experit	2055 #	1567#	878#	25/ #	475) #
_	ElasticTheo.	2069	1578	852	241	4740
H	Diff. in %	0.7	48	-3.0	-40	-0.2
4	Inf.E2.The.	2082	1519	884	273	4818
	Diff. in %	/. 3	0.9	0.8	8.8	1.6
	Experit	80/#	442#	184 #	45 [#]	1472 #
	Elastic The.	803	450	190	44	1487
V	Diff. in %	0.3	2.0	3.3	-20	1.02
-	Inf. Eg.The	811	47/	214	54	1550
	Diff. in %	/.2	6./	16.0	20,0	5.3
	Experi4	-15830" ⁴	-9747"#	-4145°*	- 885"#	-30605
M	Elastic The.	-15/78	-9800	-4154	-948	-30080
Pt4	Diff. in 90	-4./	0.7	0.1	6.9	-2.0
,	Inf. EL.The	-16496	-/1/82	-5260	-/3/2	-33250
	Diff.in%	8./	15.0	27.0	48.0	8.5
	Experil+	13903	-3090	-6105	-2126	2582
M	Elastic The	13119	-2518	-5018	-2071	4298
	Diff in %	-5,7	-18,5	-17.9	- Z. G	65.0
	Inf. Egs.The	12404	-2192	-4630	-2222	3360
	Diff. in %	-11.0	-29.0	-25.0	5.0	24.0
	Experit	-15600	-2167	28955	7215	18403
M	ElasticThe.	-14678	- 800	30036	6972	2/530
P+.14	Diff. in %	-6.0	-60.0	3,5	-3.3	17.0
	Inf. Eg.The	-14496	1508	33320	8418	27670
	Diff.in %	-7.0	200.0	14.0	16.7	50.0
	Experit	2/392	- 20388	-49082	-46608	-94686
n	Elastic The.	23556	-17930	-49474	-47350	-91198
Pt,18.	Diff.in%	10.5	-/2./	0.8	1.6	-3.7
	Inf. Eg. The	20901	-/672/	-44152	-44010	-83982
ł	27772777.					

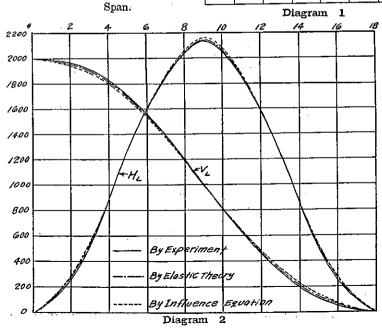
CONCLUSION.

If we examine Table 10 we will find, in some cases, that the difference in percentage is quite large. However, from the practical point of view this is not our main concern but we are interested in what the difference is in the influence values as a whole, which is shown in diagrams Diagram 1 and 2. From these diagrams it can be judged whether this Influence Equation Theory is applicable to the solution of practical problem or not.

SECOND ILLUSTRATION. RING.

The usefulness of the Influence Equation Theory can also be seen





from the illustration in connection with the analysis of a circular ring. The results

of the analysis will be compared with experimental results. Find the value of the moment, horizontal and vertical reactions at point a if concentrated loads P are applied on a circular ring having uniform thickness, as shown in Fig. 2.

Divide the ring into 12 equal segments then all the member ratio become the same let us say unity or 1.

Establish Influence Equations for this structure by inspection referring to the general equations of ring problems which were given in **Table 10** in September 1932 journal.

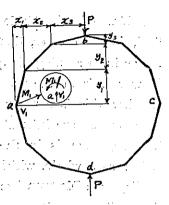


Fig. 2

In this case the member ratio is the same therefore the Influence Equations will be much simplified and since loads P were applied at the joints therefore the constant terms, α and β , disappear from equations then we have 3 Relational Moment Equations as shown in Table 11.

Table 11

٠.													
: .		M,	Mz	M4	Mo	Ma	MIO	MIZ	M14	MIS	· M18	MZO	M22
	Ź.	-2	Z	2	2	2	2	2	2	2	2	2	2
	2	- p- P24	$\phi_2 + \phi_3$	94+93	9,197	Pa+94	Pot Al	P12+913	P14+P15	916 47	P18+P19	920 421	Pz + 923
													022023

The values of ϕ and θ are as shown in Table 12.

Substituting these values into Relational Moment Equations (2) and (3) and dividing equation (1) by 2 and establishing Influence Equations we have **Table 13**.

Solving these equations we obtain,

$$M_1 = -\frac{1}{12}(5x_1 + 3x_2 + x_3)P$$

$$H_1 = 0$$

$$V_1 = \frac{1}{2}P$$

Next divide the ring into 16 equal segments and find H_1 , V_1 and M_1 by the same procedure then we have,

$$H_1=0$$
, $V_1=\frac{1}{2}P$
$$M_1=-\frac{1}{16}(7x_1+5x_2+3x_3+x_4)P$$

Table 12

ø	0
$\phi_{i} = -\phi_{i3} = \mathcal{Y}_{i}$	$\theta_1 = \theta'_{24} = \chi_1$
$\phi_2 = -\phi_{14} = 2y_1$	$\theta_z = \theta'_{23} = 2x$,
$\phi_3 = -\phi_{15} = 39, +9_2$	$\theta_3 = \theta_{22} = 3Z, +X_2$
$\phi_4 = -\phi_{16} = 3y_1 + 2y_2$	$\theta_4 = \theta_{2i} = 3\chi_i + 2\chi_2$
$\phi_5 = -\phi_{11} = 3(y_1 + y_2) + y_3$	$\theta 5 = \theta_{20} = 3(x_1 + x_2) + x_3$
$\phi_6 = -\phi_{18} = 3(\xi_1 + y_2) + 2y_3$	$\theta_6 = \theta_{19} = 3(x_1 + x_2) + 2x_3$
$\phi_7 = -\phi_{19} = 3(y_1 + y_2) + 2y_3$	$\theta_1 = \theta_{18} = 3(x_1 + x_2 + x_3) + x_3$
$\phi_8 = -\phi_{20} = 3(y_1 + y_2) + y_3$	$\theta_8 = \theta_{17} = 3(\chi_1 + \chi_2 + \chi_3) + 2\chi_3$
$\phi_g = -\phi_{21} = 34, +24_2$	$\Theta_7 = \theta_{16} = 3(Z_1 + Z_2 + 2Z_3) + Z_2$
$\phi_{10} = -\phi_{22} = 3y_1 + y_2$	$\theta_{10} = \theta_{15} = 3(\chi_1 + \chi_2 + 2\chi_3) + 2\chi_2$
$\phi_{ii} = -\phi_{23}' = 2\mathcal{J},$	$\theta_{11} = \theta_{14} = 3(\mathcal{Z}_1 + 2\mathcal{X}_2 + 2\mathcal{X}_3) + \mathcal{X}_1$
$\phi_{12} = -\phi_{24}' = y_1$	012 = 015 = 3(X,+2X2+2X3)+2X1

Comparing these two cases it will be noticed that there is similarity in the construc-

Table	13

	MI	Mz	M4	Ms	MB	Mio	MIZ	M14	MIG	MIB	M20	M22	H_{I}	V,	Mo P
4	-/	7	/	/	7	/	1	/	/	/	7.	1			
5	0	54,+4 ₂	65,+54 ₂ + 4 ₃			54,+Y ₂		54,+4 ₂	68,+54,	6(4,+4 <u>)</u> +44 ₃	64,+54,	54,+4 ₂			
6	2X,	5X,+X,	6X,+5Z, +X3	<i>ब्</i> द्रभ्यू+र्यु)	6x+7xe +11x3	1x+11X, +12X3	10X+12X +12X3	7X,+11X, +/2X3	6X,+7X,	6(x,tx <u>,</u> tx)	6X,+5X +X3	5X,1X			
7				1							-/	1	92	-ズz	0
8										-/	/		<i>y</i> ₃ _	<i>-X</i> ₃	0
9							1		-/	/			-y ₃	-X3	X3
10								-/	/				- 4z	-X2	Χz
//							-/	/	j			l	-¥,	-z,	z,
12						-/	/						-¥,	Z,	-x,
13					-/	/							-42	72	-Zz
14				-/	1								- 4 3	23	-23
15			-/	1						ļ			y_3	χ₃	0
16		-/	1				I						42	Zz	0
17	+/	/				1			1]		4,	x,	0

tion of equations and so the equations may be written in the following general equations.

$$H_1 = 0,$$
 $V_1 = \frac{1}{2}P$
$$M_1 = -\frac{P}{n} \left[\left(\frac{n}{2} - 1 \right) x_1 + \left(\frac{n}{2} - 3 \right) x_2 + \dots + x_{\frac{n}{4}} \right) \right]$$

Where n is the number of segments. For example, let us divide the ring into 36 equal segments then

$$M_1 = -\frac{P}{36}(17x_1 + 15x_2 + 13x_3 + 11x_4 + 9x_5 + 7x_6 + 5x_7 + 3x_8 + x_9)$$

$$x = r \text{ vers } \Psi$$

$$l = 2r\sin\frac{\psi}{2}$$

Substituting the values in Table 14 into above equation we have,

$$M_1 = -\frac{P}{36} \times 6.57r = -0.1825Pr$$

As the reaction at a

$$M_a = -M_1 = 0.1825 Pr$$

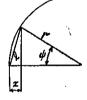
The moment at point b where load P is applied,

 $M_b = 0.3175 Pr$

From the experiments

$$M_a = 0.182 Pr$$
, $M_b = 0.318 Pr$

We can readily see from the illustrations given that this theory is not dangerous to use for practical applications.



1 .015/9r 2 .045/2r 3 .07366r 4 .09999r 5 ./2325r 6 .4279r 7 ./5198r 8 ./6837r

Table 14

Fig. 3