

## 三徑間ニシテ單扶構ヲ有スル吊橋ノ略理論

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以下論スル所ノ吊橋ノ理論ハ Principle of least workニ依ルモノニシテ廣井先生著 *Statically-indeterminate stresses*ニ負フ所頗ル大ナリ

## 第一章 吊橋ノ理論ニ關スル假定

- (一) 荷重ノ位置ノ如何ニ係ラス各吊材(Hanger)ニ於ケル張力ヲ一樣ナリト假定スルコト  
各吊材ノ張力ハ實際ニ於テ多少異ルモノナレトモ徑間大ニシテ剛扶構(Rigid stiffening truss)ヲ有スル吊橋ニ於テハ此種假定モ眞ニ近キモノナリ
- (二) 死荷重ハ扶構ニ何等應力ヲ與フルコトナク直チニ鍊條(Cable)ニ運ハル、モノナリト假定スルコト

此ノ假定ハ吊橋ノ構造如何ニ依ルモノニシテ正規狀態(Normal condition)ト正規溫度(Normal temperature)ニ於テ吊材ヲ適當ニ締メ付ケ活荷重ヲ受ケサル際ハ扶構ノ兩端カ支承ト相接觸スルノミニシテ少シモ反力ナキ如ク吊材ノ長サヲ調整スレハ此ノ假定ハ眞ナリ

- (三) 鍊條ニ働ク死荷重ヲ水平毎呎一樣ナリト假定スルコト  
徑間大ニシテ剛扶構ヲ有シ死荷重大ナル吊橋ニ於テハ鍊條ノ自重ニ比シ扶構及床構等ノ重量

頗ル大ナルヲ以テ此ノ假定モ眞ニ近シ

(四) 温度ノ變化並ニ活荷重ノ爲メニ起ル鍊條ノ撓度ヲ無視スルコト

鍊條ハ温度ノ變化並ニ活荷重ノ爲メ可ナリ大ナル撓度ヲ起スモノニシテ時トシテハ垂矢(Deflection)ノ一〇%以上ニ及フコト稀ナリトセス然レトモ理論ヲ簡單ナラシメンカ爲メ此處ニハ之ヲ無視スルモノトス

是レ所謂略理論タル所以ニシテ吊橋ノ最モ正確ナル理論ヲ研究セント欲ゼハ鍊條ノ撓度ヲ考ニ取ラサルヘカラス

(五) 扶構ヲ一本ノ桁(Beam)ト假定スルコト

普通扶構ハ高サ低ク徑間大ナルヲ以テ扶構ノ内働(Internal work)ノ計算ニ於テ之ヲ一本ノ桁ト假定スルモ大差ナシ

(六) 塔上ニ於ケル摩擦抵抗ヲ無視スルコト

普通塔(Tower)ノ頂上ニハ轉子(Roller)カ設置セラレアルヲ以テ摩擦抵抗ハ非常ニ小ナリ故ニ塔ノ内働計算ニ於テ彎曲率(Bending moment)ヲ無視セルハ此ノ假定ニ依ルモノナリ

(七) 鎮礎(Anchorages)ニ於ケル變形ヲ無視スルコト

鎮礎ニ於ケル變形(Deformation)ハ比較的小ナルモノナルカ故ニ内働計算ノ際之ヲ無視スルモ大差ナシ

## 第二章 死荷重ニ對スル鍊條ノ形狀ト其ノ水平分力

前章假定(二)及ヒ(三)ニヨリ死荷重ハ扶構ニ何等應力ヲ與フルコトナク吊材ニヨリ直ニ鍊條ニ運ハルハモノトシ且ツ水平每呎ニ一様ナリト假定ス

今中央徑間ニ於ケル水平每呎ノ死荷重ヲ $w$ トシ側徑間ニ於ケル水平每呎ノ死荷重ヲ $w_1$ ト假定ス

論 說

三徑間ニシテ單扶橋ヲ有スル吊橋ノ略理論

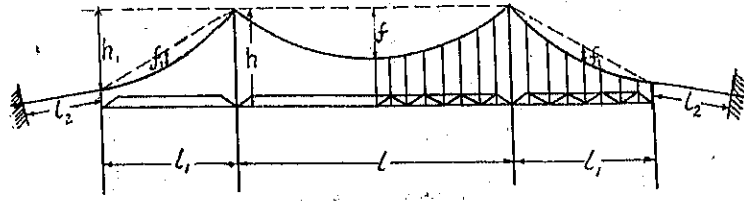


圖 一 第

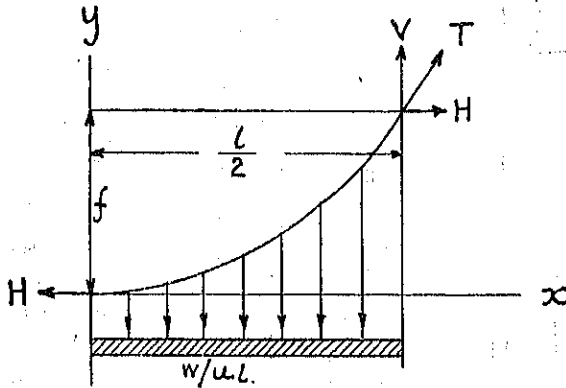


圖 二 第

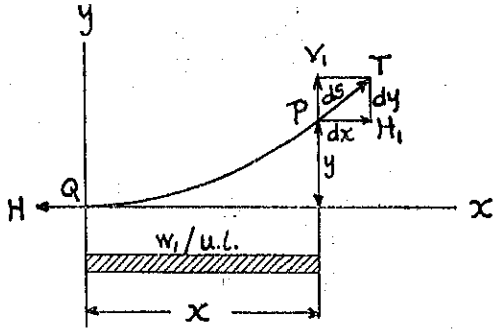


圖 三 第

レハ鍊條應力ノ水平分力ハ各部分ニ於テ相等シク且ツ鍊條カ拋線狀ヲナスコトヲ證明セン  
 今鍊條ノ水平分力ヲHトスレハ前章假定(六)ニヨリ塔上ノ摩擦抵抗ヲ無視スル  
 時ハ塔上ニ於ケル反力垂直ナルヲ以テ鍊條應力ノ水平分力Hハ鍊條ノ何レノ  
 部分ニ於テモ相等シキコト明ナリ  
 又鍊條カ拋線狀ヲナスコトハ次ノ如クシテ證明スルコトヲ得ヘシ

(第一) 中央鍊條 (Center cable)

今第二圖ノ右端ニ於テ力率ヲ取レハ

$$Hf - \frac{1}{2} w \left(\frac{l}{2}\right)^2 = 0$$

$$\therefore H = \frac{wf^2}{8f} \dots \dots (1)$$

第三圖ニ於テQPナル  
 鍊條ノ一部分ヲ考フル  
 ニ  $V_1 = w_1 x$  ナルコト明ナ  
 リ  
 又P點ノ應力ヲ  $H_1$   $V_1$  ニ  
 分解スレハ容易ニ次ノ  
 關係式ヲ得ヘシ

$$\frac{dy}{dx} = \frac{V_1}{H_1} = \frac{w_1 x}{H}$$

∞ナルトキ ∞ナルヲ以テ C=0 ナリ

$$\text{or } y = \int \frac{wx}{H} dx + C = \frac{w}{2H} x^2 + C$$

$$\therefore y = \frac{w}{2H} x^2 = \frac{4f}{l^2} x^2 \dots \dots \dots (2)$$

是レ拋線ノ方程式ニシテ鍊條カ拋線狀ヲナスコトヲ知ル  
 $\frac{dy}{dx} = \frac{8f}{l^2} x$ ナルヲ以テ中央鍊條ノ任意ノ點ニ於ケル張力 T ハ次ノ如クシテ求ムルコトヲ得ヘシ

$$T = H \frac{ds}{dx} = H \sqrt{1 + \left(\frac{dy}{dx}\right)^2} dx = H \left[ 1 + \left(\frac{8f}{l^2}\right)^2 x^2 \right]^{\frac{1}{2}} \dots \dots \dots (3)$$

(第二) 側鍊條 (Side cable)

第四圖左端ニ於テ力率ヲ取

$$H h_1 - T_1 l_1 + \frac{1}{2} w l_1^2 = 0$$

$$\therefore T = \frac{1}{2} w l_1 + \frac{H h_1}{l_1}$$

第五圖ニ於テ P Q ナル鍊條

ノ一部分ヲ考フニ  $H_1 = H$

ニシテ  $T_1 = T - w_1 x$  ナルコト

明ナリ

又鍊條上ノ任意ノ一點 P ニ

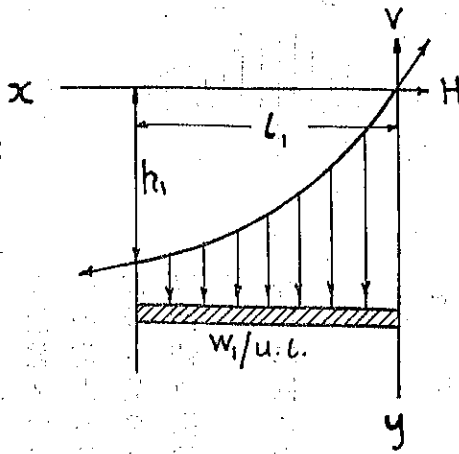


圖 四 第

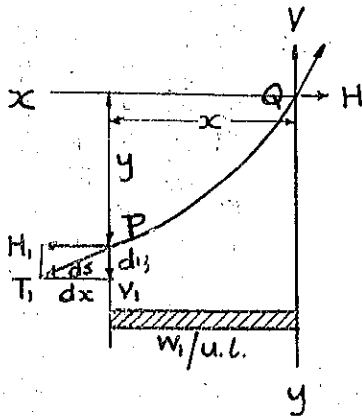


圖 五 第

於ケル應力ヲ  $H, F_1$  ニ分解スレハ容易ニ次ノ關係式ヲ得ヘシ

$$\frac{dy}{dx} = \frac{V_1}{H_1} = \frac{V - w_1 x}{H} = \frac{\frac{1}{2} w_1 l + \frac{H}{l} l_1 - w_1 x}{H}$$

$$y = \int \left( \frac{\frac{1}{2} w_1 l + \frac{H}{l} l_1 - w_1 x}{H} \right) dx + C = \frac{1}{H} \left( \frac{1}{2} w_1 l + \frac{H}{l} l_1 \right) x - \frac{1}{2H} w_1 x^2 + C$$

$s=0$  ナルトキ  $y=0$  ナルヲ以テ  $C=0$  ナリ

又  $s=\frac{l}{2}$  ナルトキ  $y=\frac{l_1}{2} + \frac{H}{F_1}$  ナルヲ以テ

$$H = \frac{w_1 l^2}{8F_1} \dots \dots \dots (4)$$

$H$  ノ値ヲ  $y$  ノ式ニ代入スレハ

$$y = \frac{4F_1}{l^2} \left( l_1 x - x^2 \right) + \frac{l_1}{l} x \dots \dots \dots (5)$$

是レ拋線ノ方程式ニシテ側鍊條モ矢張拋線狀ヲナスコトヲ知ル

$\frac{dy}{dx} = \frac{l_1 + 4F_1}{l_1} - \frac{8F_1}{l^2} x$  ナルヲ以テ側鍊條ノ任意ノ點ニ於ケル張力  $F_1$  ハ次式ノ如シ

$$F_1 = H \frac{ds}{dx} = H \sqrt{1 + \left( \frac{dy}{dx} \right)^2} = H \left\{ 1 + \left( \frac{l_1 + 4F_1}{l_1} - \frac{8F_1}{l^2} x \right)^2 \right\}^{\frac{1}{2}} \dots \dots \dots (6)$$

算式(1)及ヒ(4)ヨリ次ノ關係式ヲ得ヘシ

$$\frac{f_1}{f} = \frac{w_1 l^2}{w l^2} \dots \dots \dots (7)$$

即チ設計ノ初メニ當リ垂矢ノ決定ニ於テ中央徑間及ヒ側徑間ニ於ケル垂矢ハ上ノ關係式ヲ満足スル如ク之ヲ決定セサルヘカラス

第三章 活荷重ニ對スル鍊條ノ形狀ト其ノ水平分力

第一章假定(一)ニヨリ或任意ノ位置ニ置カレタル活荷重ニ對シ鍊條ニ働ク吊材張力(Hanger pull)ヲ水平毎呎ニ一樣ナリト假定スレハ前同様ニ鍊條應力ノ水平分力 $H$ ハ各部分ニ於テ相等シク鍊條カ常ニ拋線狀ヲナスコトヲ容易ニ證明シ得ヘシ  
今 $P$ ナル任意ノ活荷重ニ對スル水平毎呎ノ吊材張力ヲ中央徑間ニテ $p$ トシ側徑間ニテ $p_1$ トシ鍊條應力ノ水平分力ヲ $H$ トシ又中央鍊條及側鍊條ノ張力ヲ $T$ 及ヒ $T_1$ トスレハ第二章同様次ノ算式ヲ證明シ得ヘシ

$$H = \frac{p l^2}{8f} \quad \text{or} \quad p = \frac{8 H f}{l^2} \dots \dots \dots (8)$$

$$H = \frac{p_1 l_1^2}{8f_1} \quad \text{or} \quad p_1 = \frac{8 H f_1}{l_1^2} \dots \dots \dots (9)$$

$$T = H \left\{ 1 + \left( \frac{8f}{l^2} \right)^2 x^2 \right\}^{\frac{1}{2}} \dots \dots \dots (10)$$

$$T_1 = H \left\{ 1 + \left( \frac{l_1 + 4f_1}{l_1^2} - \frac{8f_1}{l_1^2} x \right)^2 \right\}^{\frac{1}{2}} \dots \dots \dots (11)$$

第四章 活荷重ヨリ起ル鍊條ノ水平分力

總テ扶構ハ下向反力ニ抗スル爲メ其ノ兩端ニ於テ鎮礎セラル、モノトス但シ鉋結ニシテ力率ハ起ラサルモノトス

第七圖ニ於テ $P_1$ ノ爲メニ起ル吊材ノ張力ヲ水平毎呎ニ付キ中央徑間ニテ $p$ トシ側徑間ニテ $p_1$ ト

右側扶構ノ彎曲率

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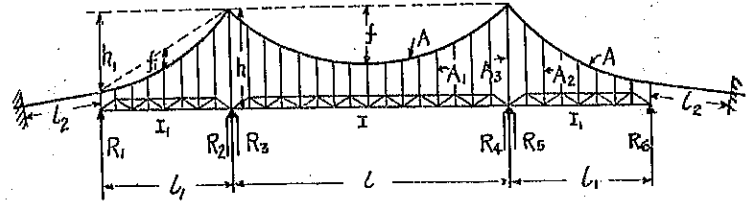


圖 六 第

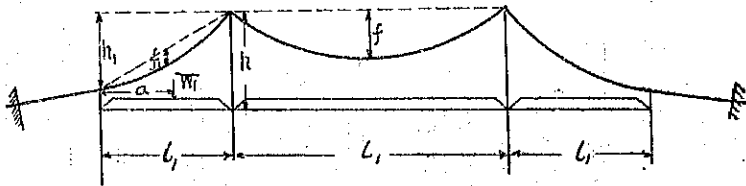


圖 七 第

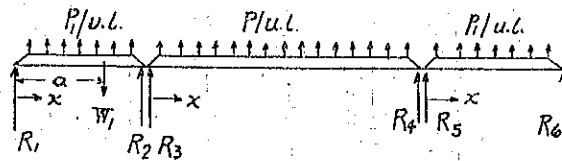


圖 八 第

$$M = -\frac{4Hf}{l} \alpha + \frac{4Hf}{l^2} \alpha^2$$

中央扶構ノ彎曲率

$$\frac{\partial M}{\partial H} = \frac{4f}{l} \left( -\alpha + \frac{\alpha^2}{l} \right)$$

$$\alpha > \alpha \quad M = \frac{1}{l_1} \left\{ W_1(l_1 - \alpha) - 4Hf_1 \right\} \alpha + \frac{4Hf_1}{l_1^2} \alpha^2 - W_1(\alpha - \alpha)$$

$$\frac{\partial M}{\partial H} = \frac{4f_1}{l_1} \left( -\alpha + \frac{\alpha^2}{l_1} \right)$$

$$\alpha < \alpha \quad M = \frac{1}{l_1} \left\{ W_1(l_1 - \alpha) - 4Hf_1 \right\} \alpha + \frac{4Hf_1}{l_1^2} \alpha^2$$

$$\frac{\partial M}{\partial H} = \frac{4f_1}{l_1} \left( -\alpha + \frac{\alpha^2}{l_1} \right)$$

左側扶構ノ彎曲率

$$R_2 = R_4 = -\frac{4}{l} Hf$$

$$R_3 = R_5 = -\frac{4}{l_1} Hf_1$$

各扶構ノ反力ハ次ノ如シ

$$R_1 = \frac{1}{l_1} \left\{ W_1(l_1 - \alpha) - 4Hf_1 \right\}$$

$$R_6 = \frac{1}{l_1} \left\{ W_1 \alpha - 4Hf_1 \right\}$$

(一) 扶構ノ内働ト其ノ微係數

スレハ算式(8)(9)ニヨリ

$$p = \frac{8Hf}{l^2} \quad p_1 = \frac{8Hf_1}{l_1^2}$$

$$M = -\frac{4Hf_1}{l_1} \alpha + \frac{4Hf_1 \alpha^2}{l_1^2} \quad \frac{dM}{dH} = \frac{4f_1}{l_1} \left( -\alpha + \frac{2\alpha^2}{l_1} \right)$$

$E$  = 鋼ノ彈率 (Modulus of elasticity)

$I$  = 中央扶構ノ惰率 (Moment of inertia)

$I_1$  = 側扶構ノ惰率

トシ腹材ノ變形ヲ省略スル時、扶構ノ總内働ハ次ノ如シ

$$\omega = \int_0^{\alpha} \frac{M^2}{2EI_1} dx + \int_a^{l_1} \frac{M^2}{2EI_1} dx + \int_0^{l_1} \frac{M^2}{2EI_1} dx + \int_0^{l_1} \frac{M^2}{2EI_1} dx$$

$$\frac{d\omega}{dH} = \int_0^{\alpha} \frac{M}{EI_1} \left( \frac{dM}{dH} \right) dx + \int_a^{l_1} \frac{M}{EI_1} \left( \frac{dM}{dH} \right) dx + \int_0^{l_1} \frac{M}{EI_1} \left( \frac{dM}{dH} \right) dx + \int_0^{l_1} \frac{M}{EI_1} \left( \frac{dM}{dH} \right) dx$$

$$= \frac{4f_1}{EI_1 l_1} \int_0^{l_1} \left[ \frac{1}{l_1} \left\{ W_1(l_1 - \alpha) - 4Hf_1 \right\} \alpha + \frac{4Hf_1 \alpha^2}{l_1^2} \right] \left( -\alpha + \frac{\alpha^2}{l_1} \right) dx$$

$$- \frac{4W_1 f_1}{EI_1 l_1} \int_a^{l_1} (x - \alpha) \left( -\alpha + \frac{\alpha^2}{l_1} \right) dx + \frac{16Hf_1^2}{EI_1^2} \int_0^{l_1} \left( -\alpha + \frac{\alpha^2}{l_1} \right)^2 dx$$

$$+ \frac{16Hf_1^2}{EI_1 l_1^2} \int_0^{l_1} \left( -\alpha + \frac{\alpha^2}{l_1} \right)^2 dx$$

$$= \frac{8H}{15E} \left( \frac{f_1^3 l_1}{I} + \frac{2f_1^2 l_1}{I_1} \right) - \frac{\alpha f_1}{3EI_1} \left( l_1 - \frac{2\alpha^2}{l_1} + \frac{\alpha^3}{l_1^2} \right) W_1 \dots \dots \dots (a)$$

(二) 鍊條ノ内働ト其ノ微係數

算式(10)及(11)ニヨリ中央鍊條及側鍊條ノ張力 $T$ 及ヒ $T_1$ ハ次ノ如シ

$$T = H \left\{ 1 + \left( \frac{8f}{l} \right)^2 \alpha^2 \right\}^{\frac{1}{2}} \quad \frac{dT}{dH} = \left\{ 1 + \left( \frac{8f}{l} \right)^2 \alpha^2 \right\}^{\frac{1}{2}}$$



$$M = -\frac{4Hf_1}{l_1} \alpha + \frac{4Hf_1 \alpha^2}{l_1^2}$$

$$\frac{dM}{dH} = \frac{4f_1}{l_1} \left( -\alpha + \frac{\alpha^2}{l_1} \right)$$

$E$  = 鋼ノ彈率 (Modulus of elasticity)

$I$  = 中央扶構ノ惰率 (Moment of inertia)

$I_1$  = 側扶構ノ惰率

トシ腹材ノ變形ヲ省略スル時ハ扶構ノ總内働ハ次ノ如シ

$$\omega = \int_0^{\alpha} \frac{M^2}{2EI_1} d\alpha + \int_{\alpha}^{l_1} \frac{M^2}{2EI_1} d\alpha + \int_0^l \frac{M^2}{2EI} d\alpha + \int_0^{l_1} \frac{M^2}{2EI_1} d\alpha$$

$$\frac{d\omega}{dH} = \int_0^{\alpha} \frac{dM}{EI_1} \left( \frac{dM}{dH} \right) d\alpha + \int_{\alpha}^{l_1} \frac{M}{EI_1} \left( \frac{dM}{dH} \right) d\alpha + \int_0^l \frac{M}{EI} \left( \frac{dM}{dH} \right) d\alpha + \int_0^{l_1} \frac{M}{EI_1} \left( \frac{dM}{dH} \right) d\alpha$$

$$= \frac{4f_1}{EI_1 l_1} \int_0^{l_1} \left[ \frac{1}{l_1} \left\{ W_1(l_1 - \alpha) - 4Hf_1 \right\} \alpha + \frac{4Hf_1 \alpha^2}{l_1^2} \right] \left( -\alpha + \frac{\alpha^2}{l_1} \right) d\alpha$$

$$- \frac{4W_1 f_1}{EI_1 l_1} \int_{\alpha}^{l_1} (\alpha - \alpha) \left( -\alpha + \frac{\alpha^2}{l_1} \right) d\alpha + \frac{16Hf_1^2}{EI l^2} \int_0^l \left( -\alpha + \frac{\alpha^2}{l} \right) d\alpha$$

$$+ \frac{16Hf_1^2}{EI_1 l_1^2} \int_0^{l_1} \left( -\alpha + \frac{\alpha^2}{l_1} \right) d\alpha$$

$$= \frac{8H}{15E} \left( \frac{f_1^2 l}{I} + \frac{2f_1^2 l_1}{I_1} \right) - \frac{\alpha f_1}{3EI_1} \left( l_1 - \frac{2\alpha^2}{l_1} + \frac{\alpha^3}{l_1^2} \right) W_1 \dots \dots \dots (a)$$

(二) 鍊條ノ内働ト其ノ微係數

算式(10)及(11)ニヨリ中央鍊條及側鍊條ノ張力 $T$ 及ヒ $T_1$ ハ次ノ如シ

$$T = H \left\{ 1 + \left( \frac{8f}{l^2} \right) \alpha^2 \right\}^{\frac{1}{2}}$$

$$\frac{dT}{dH} = \left\{ 1 + \left( \frac{8f}{l^2} \right) \alpha^2 \right\}^{\frac{1}{2}}$$

$$+ \frac{1}{2} \left[ 1 + \left( \frac{h_1 - 4f_1}{l_1} \right)^2 \right] \\ = \frac{2H}{EA} \left\{ \frac{l}{2} + l_1 + l_2 + \frac{4f^2}{l} + \frac{3h_1^2 + 16f_1^2}{2l_1} \right\} \quad \text{nearby} \quad \dots \dots \dots (b)$$

但シ  $\frac{d\omega}{dH}$  ノ眞値ハ次ノ如キモノナレトモ (b) 式ノ與フル略値ト大差ナキヲ以テ (b) 式ヲ採用ス

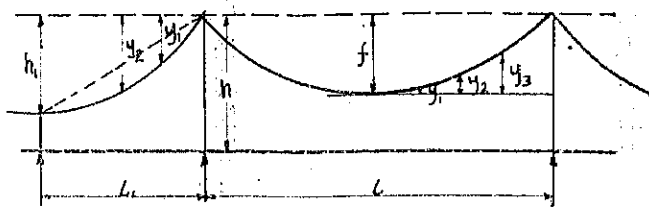
$$\frac{d\omega}{dH} = \frac{2H}{EA} \left[ l \left( 1 + \frac{16f^2}{l^2} \right)^{\frac{3}{2}} \left( \frac{5}{16} + \frac{2f^2}{l^2} \right) + \frac{3}{64} \frac{l^2}{f} \log_0 \left\{ \left( 1 + \frac{16f^2}{l^2} \right)^{\frac{3}{2}} + \frac{4f}{l} \right\} \right] \\ + \frac{2H}{EA} \left[ -l_1 \frac{(h_1 - 4f_1)}{64f_1} \left\{ 1 + \left( \frac{h_1 - 4f_1}{l_1} \right)^2 \right\}^{\frac{3}{2}} \left\{ 5 + 2 \left( \frac{h_1 - 4f_1}{l_1} \right)^2 \right\} \right. \\ \left. + \frac{l_1 (h_1 + 4f_1)}{64f_1} \left\{ 1 + \left( \frac{h_1 + 4f_1}{l_1} \right)^2 \right\}^{\frac{3}{2}} \left\{ 5 + 2 \left( \frac{h_1 + 4f_1}{l_1} \right)^2 \right\} \right. \\ \left. + \frac{3l_1^2}{64f_1} \log_0 \frac{\left\{ 1 + \left( \frac{h_1 + 4f_1}{l_1} \right)^2 \right\}^{\frac{3}{2}} + \frac{h_1 + 4f_1}{l_1}}{\left\{ 1 + \left( \frac{h_1 - 4f_1}{l_1} \right)^2 \right\}^{\frac{3}{2}} + \frac{h_1 - 4f_1}{l_1}} \right] \\ + \frac{2H}{EA} \left\{ 1 + \left( \frac{h_1 - 4f_1}{l_1} \right)^2 \right\}^{\frac{3}{2}} l_2$$

(三) 吊材ノ内働ト其ノ微係數

(A) 中央徑間ノ吊材

n ヲ中央扶構ノ構格數 (Panel number) トスルハ n ノ格間長 (Panel length) トスル

$$y_1 + y_2 + \dots + y_{n-1} = \frac{4f}{l^2} \left( \frac{l}{n} \right)^2 + \frac{4f}{l^2} \left( \frac{2l}{n} \right)^2 + \dots + \frac{4f}{l^2} \left\{ \left( \frac{n-1}{2} \right) \frac{l}{n} \right\}^2$$



第九圖

$$= \frac{4f}{l^2} \left( \frac{l}{n} \right)^2 \{ 1^2 + 2^2 + \dots + \left( \frac{n-1}{2} \right)^2 \}$$

$$= \frac{1}{3} \frac{f}{n} \left( \frac{n}{2} - 1 \right) (n-1)$$

中央徑間ニ於ケル吊材ノ全長ヲ  $L_1$  トスレハ

$$L_1 = (h-f)(n-1) + \frac{2}{3} f \left( \frac{n}{2} - 1 \right) (n-1) = n \left( h - \frac{2}{3} f \right) \quad \text{nearby}$$

今  $S_1$  ヲ中央徑間ニ於ケル各吊材ノ張力トスレハ

$$S_1 = p \left( \frac{l}{n} \right) = \frac{8Hf}{nl} \quad \frac{dS_1}{dH} = \frac{8f}{nl}$$

(B) 側徑間ノ吊材

$n_1$  ヲ側扶構ノ構格數トスレハ  $\frac{l_1}{n_1}$  其ノ格間長トナル

$$y_1 + y_2 + \dots + y_{n_1} = \frac{4f_1 l_1}{l_1^2 n_1} \left[ \frac{l_1}{n_1} (1+2+\dots+n_1) \right]$$

$$= \frac{4f_1}{l_1^2} \left( \frac{l_1}{n_1} \right)^2 \{ 1^2 + 2^2 + \dots + n_1^2 \}$$

$$+ \frac{h_1}{l_1} \frac{l_1}{n_1} (1+2+\dots+n_1)$$

$$= (n_1+1) \left\{ \frac{l_1}{2} + \frac{2}{3} f_1 \left( 1 - \frac{1}{n_1} \right) \right\} = (n_1+1) \left( \frac{l_1}{2} + \frac{2}{3} f_1 \right) \quad \text{nearby}$$

側徑間ニ於ケル吊材ノ全長ヲ  $L_2$  トスレハ

$$L_2 = l n_1 - (n_1+1) \left( \frac{l_1}{2} + \frac{2}{3} f_1 \right) = n_1 \left( h - \frac{l_1}{2} - \frac{2}{3} f_1 \right) \quad \text{nearby}$$

今  $S_2$  ヲ側徑間ニ於ケル各吊材ノ張力トスレハ

$$S_2 = p_1 \left( \frac{l}{n_1} \right) = \frac{8 H f_1}{n_1 l} \quad \frac{dS_2}{dH} = \frac{8 f_1}{n_1 l}$$

今  $A_1$  及ヒ  $A_2$  ヲ中央徑間及側徑間ニ於ケル各吊材ノ斷面積トスレハ全吊材ニ於ケル内働ノ總和ハ次ノ如シ

$$\omega = \frac{S_1^2 L_1}{2EA_1} + \frac{S_2^2 L_2}{2EA_2}$$

$$\begin{aligned} \frac{d\omega}{dH} &= \frac{S_1 L_1}{EA_1} \left( \frac{dS_1}{dH} \right) + 2 \frac{S_2 L_2}{EA_2} \left( \frac{dS_2}{dH} \right) \\ &= 64 \frac{H}{E} \left\{ \frac{f^2}{A_1 n_1^2} \left( h - \frac{2}{3} f \right) + \frac{2 f_1^2}{A_2 n_2^2} \left( h - \frac{l_2}{2} - \frac{2}{3} f_1 \right) \right\} \dots \dots \dots (c) \end{aligned}$$

(四) 塔ノ内働ト其ノ微係數

中央鍊條及ヒ側鍊條ノ方程式ハ算式(2)及ヒ(5)ニヨリ

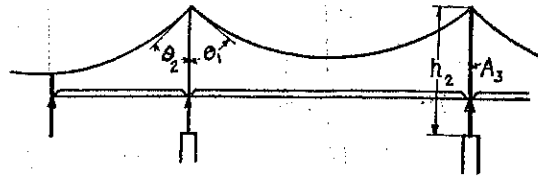
$$y = \frac{4f}{l^2} x^2 \quad \text{center cable}$$

$$y = \frac{4f_1}{l_1^2} (l_1 x - x^2) + \frac{l_2}{l_1} x \quad \text{side cable}$$

$$\frac{dy}{dx} = \frac{8f}{l} x \quad \cot \theta_1 = \frac{4f}{l}$$

$$\frac{dy}{dx} = \frac{h_1 + 4f_1}{l_1} - \frac{8f_1}{l_1^2} x \quad \cot \theta_2 = \frac{h_1 + 4f_1}{l_1}$$

塔上ニ於ケル反力垂直ナルヲ以テ塔ノ受クル全應力  $S$  ハ次ノ如シ



第十圖

第一章假定(六)ニヨリ塔上ノ摩擦抵抗ヲ無視スル時ハ塔ニ於ケル内働ノ總和ハ  
 $h_2$ ヲ塔ノ高サトシ $A_3$ ヲ塔ノ平均斷面積トスレハ次ノ如シ

$$S = H \cos \theta_1 + H \cos \theta_2 = H \left( \frac{4f}{l} + \frac{h_1 + 4f_1}{l_1} \right) \quad \frac{dS}{dH} = \left( \frac{4f}{l} + \frac{h_1 + 4f_1}{l_1} \right)$$

$$\omega = 2 \frac{S^2 h_2}{2EA_3} \quad \frac{d\omega}{dH} = 2 \frac{Sh_2}{EA_3} \left( \frac{dS}{dH} \right)$$

$$\frac{d\omega}{dH} = \frac{2H}{EA_3} \left( \frac{4f}{l} + \frac{h_1 + 4f_1}{l_1} \right)^2 h_2 \dots \dots \dots (d_1)$$

(五) 餘條ノ水平分力互ノ決定

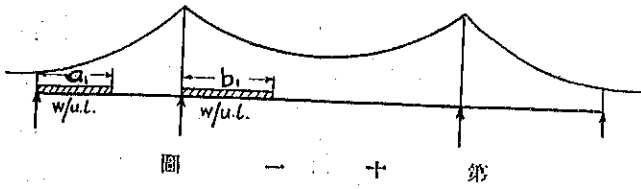
Castigliano ノ第二定理ニヨリ  $H$ ハ構造物ニ於ケル内働ノ總和ヲ最小ナラシムルモノナラサルノカラス

$$\therefore \frac{d\omega}{dH} = \text{Equation (a)} + \text{Equation (b)} + \text{Equation (c)} + \text{Equation (d)} = 0$$

上ノ方程式ヨリ次ノ結果ヲ得ル

$$H = \left[ \frac{\frac{\alpha f_1}{3l} \left( l - \frac{2a^2}{l} + \frac{a^2}{l_1^2} \right) W_1}{\frac{8}{15} \left( \frac{f^2 l}{I} + \frac{2f^2 l_1}{I} \right) + \frac{2}{A} \left( \frac{l}{2} + l_1 + l_2 + \frac{4f^2}{l} + \frac{3h_2^2 + 16f_1^2}{2l_1} \right) + 64 \left\{ \frac{f^2}{A_1 m^2 E} \left( h - \frac{2}{3} f \right) + \frac{2f_1^2}{A_2 m_1 l_1^2} \left( h - \frac{h_2}{2} - \frac{2}{3} f_1 \right) \right\} + \frac{2}{A_3} \left( \frac{4f}{l} + \frac{h_1 + 4f_1}{l_1} \right)^2 h_2} \right] \dots \dots \dots (12)$$

吊材及塔ノ影響ハ頗ル小ナルヲ以テ之ヲ省略スル時ハ(14) (15) (16) (17) 項ヲ省略スレハ宜シ



$$H = \frac{8 \left( \frac{f_1^2}{15I} + \frac{2f_1^2 l_1}{I} \right) + \frac{2}{A} \left( \frac{l}{2} + l_1 + l_2 + \frac{4f_1^2}{l} + \frac{3l_1^2 + 16f_1^2}{2l} \right) \frac{a_1 f_1}{3l_1} \left( l_1 - \frac{2a_1^2}{l} + \frac{a_1^3}{l^2} \right) W_1 \dots (13)$$

$w$  ナル等布荷重カ  $a_1$  マテ乘リシ場合ニハ算式(12) 及ヒ(13) ノ分子ニ於テ  $W_1$  ノ代リニ  $w$  ヲ入レ  $a_1$  ノ代リニ  $w$  ヲ置キヨリ  $a_1$  マテ積分スレハ宜シ

$$H = \frac{\frac{a_1^2 f_1}{3l_1} \left( l_1 - \frac{a_1^2}{2l} + \frac{a_1^3}{5l_1^2} \right) w}{\text{Denominator eq. (12) or (13)}} \dots (14)$$

左側徑間カ全部等布荷重ヲ受ケタル場合ハ次ノ如シ

$$H = \frac{\frac{f_1 l_1^3}{15l_1} w}{\text{Denominator eq. (12) or (13)}} \dots (15)$$

同様ニシテ  $W_2$  ナル荷重ニ對スル鍊條ノ水平分力  $H$  ヲ求ムレハ次ノ如シ

$$H = \frac{\frac{b f}{3I} \left( l - \frac{2b^2}{l} + \frac{b^3}{l^2} \right) W_2}{\text{Denominator eq. (12) or (13)}} \dots (16)$$

$w$  ナル等布荷重カ  $b_1$  マテ乘リシトキモ

$$H = \frac{\frac{b_1^2 f}{3I} \left( l - \frac{b_1^2}{2l} + \frac{b_1^3}{5l^2} \right) w}{\text{Denominator eq. (12) or (13)}} \dots (17)$$

$$H = \frac{fT_w}{15f} \dots \dots \dots (18)$$

Denominator eq. (12) or (13)

第五章 各部材ノ最大應力

(一) 鍊條ノ水平分力ノ最大ナル場合

死荷重ヨリ起ル鍊條ノ水平分力  $H_w$  ハ算式(1)或ハ(4)ニヨリ容易ニ之ヲ求ムルコトヲ得ヘシ

$$H_w = \frac{wl^2}{8f} \quad \text{or} \quad H_w = \frac{wl^2}{8f_1}$$

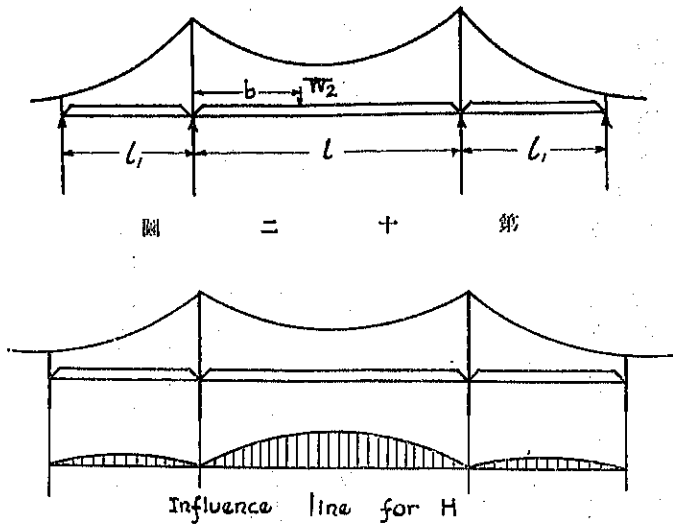
活荷重ノ爲メニ起ル鍊條ノ水平分力  $H_p$  ノ最大トナル場合ハ  $H_p$  ノ感線 (Influence line) ヲ畫ケハ明ニシテ其ノ大體ノ形狀ハ第十三圖ノ如シ

又死荷重及ヒ活荷重ヨリ起ル鍊條ノ張力ハ算式(3)(6)(10)ニヨリ

$$T = (H_w + H_p) \left\{ 1 + \left( \frac{8f}{l^2} \right)^2 x^2 \right\}^{\frac{1}{2}} \quad \text{center cable}$$

$$T_1 = (H_w + H_p) \left\{ 1 + \left( \frac{l_1 + 4f_1}{l_1} - \frac{8f_1}{l_1^2} x \right)^2 \right\}^{\frac{1}{2}} \quad \text{side cable}$$

上ノ式ヨリ鍊條ノ張力ハ塔ノ頂上ニ於テ最大ナルコト



第二十圖

第二十圖

明ニシテ其ノ値ハ次ノ如シ

1300

$$T_{max} = (H_w + H_p) \left\{ 1 + \left( \frac{4f}{l} \right)^2 \right\}^{\frac{1}{2}} \quad \text{center cable}$$

$$T_{max} = (H_w + H_p) \left\{ 1 + \left( \frac{l_1 + 4f_1}{l} \right)^2 \right\}^{\frac{1}{2}} \quad \text{side cable}$$

(二) 吊材ニ於ケル最大ナル張力

$w$  or  $w_1$  = 死荷重ヨリ起ル中央徑間及側徑間ニ於ケル水平每呎ノ吊材張力

$p$  or  $p_1$  = 活荷重ヨリ起ル中央徑間及側徑間ニ於ケル最大ナル水平每呎ノ吊材張力

$\frac{l}{n}$  or  $\frac{l_1}{n_1}$  = 中央扶構及側扶構ノ格間長

トス吊材ノ受クル最大ナル張力ハ次式ノ如シ

$$(w+p)\frac{l}{n} = \left( w + \frac{8H_w f}{l} \right) \frac{l}{n} \quad \text{center span hanger}$$

$$(w_1+p_1)\frac{l_1}{n_1} = \left( w_1 + \frac{8H_w f_1}{l_1} \right) \frac{l_1}{n_1} \quad \text{side span hanger}$$

(三) 側扶構カ最大ナル應力ヲ受クル場合

一般ニ扶構ハ死荷重ヨリ少シモ應力ヲ受ケサルモノトス

側扶構ハ荷重ノ位置ノ如何ニヨリトMoment及ヒトShearヲ受クルモノニシテ其ノ感線ノ大體ノ形狀ハ第十四圖及第十五圖ノ如シ

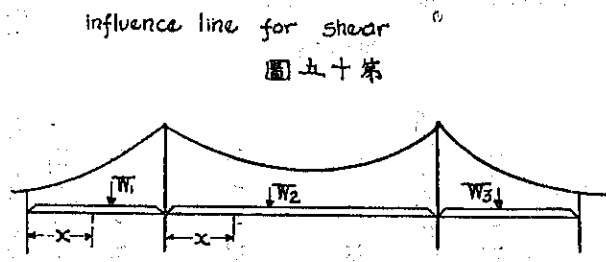
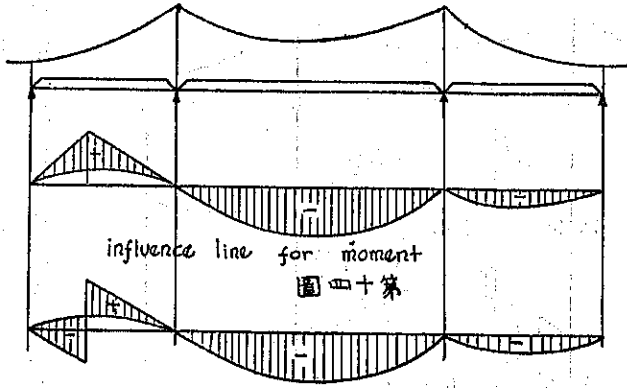
又側扶構ノ任意點 $w$ ニ於ケルBending moment及ヒShearハ次ノ如シ

Bending moment at any point  $w$



論 說 三徑間ニシテ單扶構ヲ有スル吊橋ノ略理論

(四) 中央扶構カ最大ナル應力ヲ受クル場合



due to  $W_1$

$$\left\{ \begin{aligned} M &= \frac{1}{l_1} \left[ W_1(l_1 - a) - 4Hf_1 \right] x + \frac{4Hf_1}{l_1^2} x^2 \\ M &= \frac{1}{l_2} \left[ W_1(l_1 - a) - 4Hf_1 \right] x + \frac{4Hf_1}{l_2^2} x^2 - W_1(x - a) \end{aligned} \right.$$

for  $x < a$

for  $x > a$

due to  $W_2$      $M = -\frac{4Hf_1}{l_1} x + \frac{4Hf_1}{l_1^2} x^2$

due to  $W_3$      $M = -\frac{4Hf_1}{l_1} x + \frac{4Hf_1}{l_1^2} x^2$

Shear at any point  $x$

due to  $W_1$

$$\left\{ \begin{aligned} S &= \frac{1}{l_1} \left[ W_1(l_1 - a) - 4Hf_1 \right] + \frac{8Hf_1}{l_1^2} x \\ S &= \frac{1}{l_2} \left[ W_1(l_1 - a) - 4Hf_1 \right] + \frac{8Hf_1}{l_2^2} x - W_1 \end{aligned} \right.$$

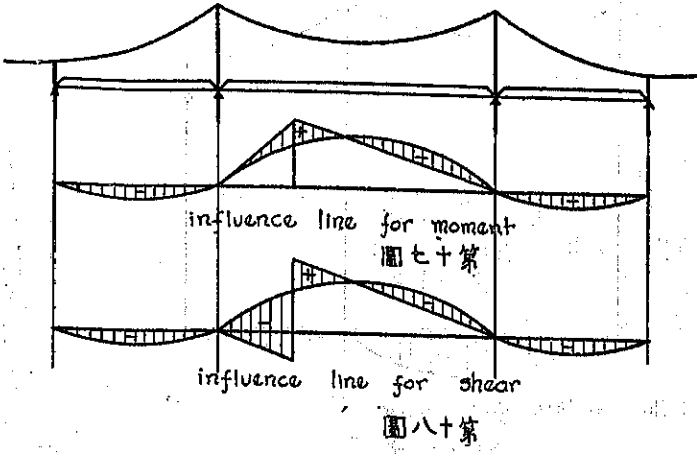
for  $x < a$

for  $x > a$

due to  $W_2$      $S = -\frac{4Hf_1}{l_1} + \frac{8Hf_1}{l_1^2} x$

due to  $W_3$      $S = -\frac{4Hf_1}{l_1} + \frac{8Hf_1}{l_1^2} x$

中央扶構モ荷重ノ位置ノ如何ニヨリト Moment 及ヒト Shear ヲ受クルモノニシテ其ノ感線ハ第十  
七圖及ヒ第十八圖ニ示スカ如シ  
又中央扶構ノ任意點  $x$  ニ於ケル Bending moment 及ヒ Shear 之ノ次ノ如シ



Bending moment at any point  $x$

due to  $W_1$   $M = -\frac{4Hf}{l}x + \frac{4Hf}{l^2}x^2$

due to  $W_2$

$$M = \frac{1}{l} \left\{ W_2(a-b) - 4Hf \right\} x + \frac{4Hf}{l^2} x^2 - W_2(x-b)$$

for  $x < b$

due to  $W_3$

$$M = -\frac{4Hf}{l}x + \frac{4Hf}{l^2}x^2$$

Shear at any point  $x$

due to  $W_1$

$$S = -\frac{4Hf}{l} + \frac{8Hf}{l^2}x$$

due to  $W_2$

$$S = \frac{1}{l} \left\{ W_2(a-b) - 4Hf \right\} + \frac{8Hf}{l^2}x$$

for  $x < b$

$$S = \frac{1}{l} \left\{ W_2(a-b) - 4Hf \right\} + \frac{8Hf}{l^2}x - W_2$$

for  $x > b$

due to  $W_3$

$$S = -\frac{4Hf}{l} + \frac{8Hf}{l^2}x$$

温度ノ變化ヨリ起ル熱應力 (Temperature stress) ハ扶構ノ剛性 (Stiffness) ニ歸因スルモノニシテ次ノ  
 二ノ解法ニ就テ述ヘントス

(4) 第一解法

dsヲ極小ナル曲線ノ長トスレハ

$$ds = \sqrt{1 + \left(\frac{dy}{dx}\right)^2} dx = \left\{1 + \left(\frac{8f}{l^2}\right)^2 x^2\right\}^{\frac{1}{2}} dx \quad \text{for center cable}$$

$$ds = \sqrt{1 + \left(\frac{dy}{dx}\right)^2} dx = \left\{1 + \left(\frac{l_1 + 4f_1}{l_1} - \frac{8f_1}{l_1^2} x\right)^2\right\}^{\frac{1}{2}} dx \quad \text{for side cable}$$

今鍊條ノ全長ヲLトスレハ

$$L = 2l_2 + 2 \int_0^{x^2} \left\{1 + \left(\frac{8f}{l^2}\right)^2 x^2\right\}^{\frac{1}{2}} dx + 2 \int_0^{l_1} \left\{1 + \left(\frac{l_1 + 4f_1}{l_1} - \frac{8f_1}{l_1^2} x\right)^2\right\}^{\frac{1}{2}} dx$$

$$= l + 2l_1 + 2l_2 + \frac{8f^2}{3l} + \frac{3h_1^2 + 16f_1^2}{3l_1} \quad \text{nearby}$$

温度カ正規温度 (Normal temperature) ヨリハ丈ケ昇降スル時ヲ伸率トシ4f4lヲ垂矢ノ變化トスレ

$$L = \left(1 + 2l_1 + 2l_2 + \frac{8f^2}{3l} + \frac{3h_1^2 + 16f_1^2}{3l_1}\right) (1 \pm \theta t)$$

$$= l + 2l_1 + 2l_2 + \frac{8(f \pm 4f_1)^2}{3l} + \frac{3h_1^2 + 16(f_1 \pm 4f_1)^2}{3l_1} \dots \dots \dots (a)$$

温度ノ昇降ニ從ツテ鍊條及ヒ扶構ハ共ニ下向或ハ上向ノ撓度ヲ起スモノニシテ其ノ撓度ノ大サ  
 ハ兩者相等シカラスト雖モ其ノ差頗ル小ナルヲ以テ是等ヲ相等シト假定シ且ツ徑間長ニ變化ナ

シト假定スル時ハ容易ニ次ノ關係式ヲ得ヘシ  
 今溫度ノ變化ヨリ起ル扶構ノ撓度ヲ $J$ 及ヒ $J_1$ トシ吊材ノ張力ヲ水平毎呎ニ $P$ 及ヒ $P_1$ トスレハ撓  
 度ノ理論ニヨリ

$$J/f = \frac{5P_1^2 L^3}{384EI} \quad \text{or} \quad P_1 = \frac{384EI}{5L^3} J/f \dots \dots \dots (1)$$

$$J/f_1 = \frac{5P_1^2 L^3}{384EI} \quad \text{or} \quad P_1 = \frac{384EI}{5L^3} J/f_1 \dots \dots \dots (2)$$

又算式(7)ニヨリ

$$\frac{f_1 + J_1}{f_1 + J_1} = \frac{P_1^2 L^3}{P_1^2 L^3} = \frac{P_1^2 L^3}{384EI J/f}$$

$$\therefore P_1 = \frac{f_1 + J_1}{f_1 + J_1} \times \frac{384EI}{5L^3} J/f = \frac{384EI}{5L^3} J/f \quad \text{nearly} \dots \dots \dots (3)$$

(c) (d) 二式ヨリ

$$J/f_1 = \frac{f_1 + J_1}{f_1 + J_1} J/f \dots \dots \dots (4)$$

(c) 式ニ於ケル $J_1$ ノ値ヲ (d) 式ニ入ルノ時ニ次ノ式ヲ得ヘシ

$$\pm \left( 1 + 2l_1 + 2l_2 + \frac{8f^2}{3l} + \frac{3l_1^2 + 16f^2}{3l} \right) g_1 = \frac{8}{3l} \left[ \pm 2f J/f + \frac{16}{3l} \left[ \pm 2l_1 J_1 + (J/f)^2 \right] \right]$$

(4f)<sup>2</sup> 及 (4f<sub>1</sub>)<sup>2</sup> ナル項ヲ省略スルトキニ

$$\left( 1 + 2l_1 + 2l_2 + \frac{8f^2}{3l} + \frac{3l_1^2 + 16f^2}{3l} \right) g_1 = \frac{8}{3l} 2f J/f + \frac{16}{3l} 2f_1 \left( \frac{f_1 + J_1}{f_1 + J_1} \right) J/f \quad \text{nearly}$$

$$\therefore \Delta f = \frac{(l + 2l_1 + 2l_2 + \frac{8f^2}{3l} + \frac{3l_1^2 + 16f_1^2}{3l}) \rho_c}{\frac{16}{3l} f + \frac{32}{3} \frac{f^2 l_1}{f^2 l_1}} \quad \text{... (19)}$$

故ニ中央徑間及側徑間ノ吊材ノ水平每呎ノ張力  $\rho_c$  及ヒ  $\rho_c'$  ハ次ノ如シ

$$\rho_c = + \frac{384EI}{5l^3} \Delta f \quad \rho_c' = + \frac{384fEI}{5f^2 l_1^2} \Delta f$$

又温度ノ變化ヨリ起ル鑄條ノ水平分力  $H_c$  ハ次ノ如シ

$$H_c = + \frac{E(l + 2l_1 + 2l_2 + \frac{8f^2}{3l} + \frac{3l_1^2 + 16f_1^2}{3l}) \rho_c}{9(\frac{f^2 l_1}{I} + \frac{2f^2 l_1}{I_1})} \quad \text{... (20)}$$

但シ温度降リシ時ハ正號ヲ用ヒ温度昇リシ時ハ負號ヲ用フルモノトス  
又吊材ノ熱應力ハ次ノ如シ

$$\rho_c \left( \frac{l}{n} \right) = \frac{8H_c f}{nl} \quad \rho_c' \left( \frac{l_1}{n_1} \right) = \frac{8H_c' f_1}{n_1 l_1}$$

又扶構ノ Bending moment 及ヒ Shear ハ次ノ如シ

For side stiffening truss

$$M = - \frac{4H_c f_1}{l_1} \omega + \frac{4H_c' f_1}{l_1^2} \omega^2$$

$$S = - \frac{4H_c f_1}{l_1} + \frac{8H_c' f_1}{l_1^2} \omega$$

For central stiffening truss

$$M = -\frac{4H_1 f}{l} \omega + \frac{4H_1 f}{r} \omega^2$$

$$S = -\frac{4H_1 f}{l} \omega + \frac{8H_1 f}{r} \omega^2$$

(B) 第二解法

温度ノ變化ヨリ起ル熱應力ハ又次ノ如クシテ其ノ略値ヲ求メ得ヘシ  
 今温度カ正規温度ヨリ $\rho$ 丈ケ降下シタル場合ヲ考ヘ其ノ時ニ起レル鑱條應力ノ水平分力ヲ $H_1$ トス

又温度ノ變化ノ爲メニ起レル内働ノ總和ハ次ノ如クシテ其ノ略値ヲ見出シ得ヘシ

(一) 扶條ノ内働ト其ノ微係數

$$\omega = 2 \int_0^{l_1} \frac{M^2}{2EI} dx + \int_0^l \frac{M^2}{2EI} dx$$

$$\frac{d\omega}{dH_1} = 2 \int_0^{l_1} \frac{M}{EI} \left( \frac{dM}{dH_1} \right) dx + \int_0^l \frac{M}{EI} \left( \frac{dM}{dH_1} \right) dx$$

$$= \frac{32H_1 f^2}{EI l^2} \int_0^{l_1} \left( -a + \frac{x^2}{l_1} \right) dx + \frac{16H_1 f^2}{EI r^2} \int_0^l \left( -a + \frac{x^2}{l} \right) dx$$

$$= \frac{8H_1}{15EI} \left\{ \frac{f^2 l}{l_1} + \frac{2f^2 l_1}{l_1} \right\} \dots \dots \dots (2)$$

(二) 鑱條ノ内働ト其ノ微係數

温度ノ變化ノ爲メ鑱條ニ起ル内働ハ次ノ如シ

$$\omega = 2 \int_0^{l_1} \frac{T^2 ds}{2EA} + 2 \int_0^{l_1} \frac{T_1^2 ds}{2EA} + 2 \int_0^{l_2} \frac{T_2^2 ds}{2EA} - 2 \int_0^{l_1} T(\theta_1 ds) - 2 \int_0^{l_1} T_1(\theta_1 ds) - 2T_1(\theta_1 l_1)$$

$$\frac{d\omega}{dH_c} = 2 \int_0^{\frac{l}{2}} \frac{T}{EA} \left( \frac{dT}{dH_c} \right) ds + 2 \int_0^{l_1} \frac{T_1}{EA} \left( \frac{dT_1}{dH_c} \right) ds + 2 \frac{T_2^2}{EA} \left( \frac{dT_2}{dH_c} \right)$$

$$- 2 \int_0^{\frac{l}{2}} \left( \frac{dT}{dH_c} \right) \theta t ds - 2 \int_0^{l_1} \left( \frac{dT_1}{dH_c} \right) \theta t ds - 2 \left( \frac{dT_2}{dH_c} \right) \theta t l_2$$

$$= \frac{2H_c}{EA} \left[ \int_0^{\frac{l}{2}} \left\{ 1 + \left( \frac{8f}{l} \right)^2 x^2 \right\}^{\frac{5}{2}} dx + \int_0^{l_1} \left\{ 1 + \left( \frac{l_1 + 4f_1}{l_1} - \frac{8f_1 x}{l_1^2} \right)^2 \right\}^{\frac{5}{2}} dx + l_2 \left\{ 1 + \left( \frac{l_1 - 4f_1}{l_1} \right)^2 \right\} \right]$$

$$- 2\theta t \left[ \int_0^{\frac{l}{2}} \left\{ 1 + \left( \frac{8f}{l} \right)^2 x^2 \right\} dx + \int_0^{l_1} \left\{ 1 + \left( \frac{l_1 + 4f_1}{l_1} - \frac{8f_1 x}{l_1^2} \right)^2 \right\} dx + l_2 \left\{ 1 + \left( \frac{l_1 - 4f_1}{l_1} \right)^2 \right\} \right]$$

$$= \frac{2H_c}{EA} \left\{ \frac{l}{2} + l_1 + l_2 + \frac{4f^2}{l} + \frac{3l_1^2 + 16f_1^2}{2l_1} \right\} - 2\theta t \left\{ \frac{l}{2} + l_1 + l_2 + \frac{8f^2}{3l} + \frac{3l_1^2 + 16f_1^2}{3l_1} \right\} \dots \dots \dots (6)$$

(三) 吊材の内働、其ノ微係數

$$\omega = \frac{S_1^2 L_1}{2EA_1} + 2 \frac{S_2^2 L_2}{2EA_2} - S_1(\theta t L_1) - 2S_2(\theta t L_2)$$

$$\frac{d\omega}{dH_c} = \frac{S_1 L_1}{EA_1} \left( \frac{dS_1}{dH_c} \right) + 2 \frac{S_2 L_2}{EA_2} \left( \frac{dS_2}{dH_c} \right) - \left( \frac{dS_1}{dH_c} \right) \theta t L_1 - 2 \left( \frac{dS_2}{dH_c} \right) \theta t L_2$$

$$= \frac{64H_c}{E} \left\{ \frac{f^2}{4l_1^2} \left( h - \frac{2}{3}f \right) + \frac{2f_1^2}{A_2 l_1^2} \left( h - \frac{h_1}{2} - \frac{2}{3}f_1 \right) \right\}$$

$$- 2\theta t \left\{ \frac{4f}{l} \left( h - \frac{2}{3}f \right) + \frac{8f_1}{l_1} \left( h - \frac{h_1}{2} - \frac{2}{3}f_1 \right) \right\} \dots \dots \dots (6)$$

(四) 塔ノ内働ト其ノ微係數

$$\omega = 2 \frac{S^2 h_2}{2EA_3} + 2S(\theta h_2)$$

$$\frac{d\omega}{dH_1} = 2 \frac{S h_2}{EA_3} \left( \frac{dS}{dH_1} \right) + 2\theta h_2 \left( \frac{dS}{dH_1} \right)$$

$$= \frac{2H_1 h_2}{EA_3} \left( \frac{4f}{l} + \frac{h_1 + 4f_1}{l_1} \right)^2 + 2\theta \left( \frac{4f}{l} + \frac{h_1 + 4f_1}{l_1} \right) h_2 \dots \dots \dots (d)$$

(五) 水平分力  $H_1$  ノ決定

Castigliano ノ第二定理ニヨリ

$$\frac{d\omega}{dH_1} = \text{Equation (a)} + \text{Equation (b)} + \text{Equation (c)} + \text{Equation (d)} = 0$$

上ノ方程式ヨリ次ノ結果ヲ得ルン

$$H_1 = \pm \frac{2E\theta \left[ \left( \frac{l}{2} + l_1 + l_2 + \frac{8f^2}{3l} + \frac{3h_1^2 + 16f_1^2}{3l_1} \right) + \frac{4f}{l} \left( h - \frac{2}{3}f \right) + \frac{8f_1}{l_1} \left( h - \frac{h_1}{2} - \frac{2}{3}f_1 \right) - \left( \frac{4f}{l} + \frac{h_1 + 4f_1}{l_1} \right) h_2 \right] t}{\text{Denominator eq. (12)}}$$

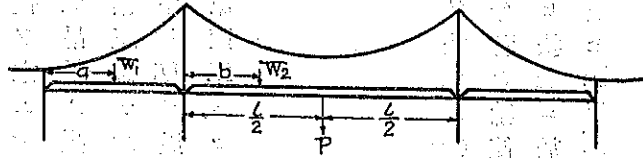
..... (21)

吊材及塔ノ影響頗ル小ナルヲ以テ之ヲ無視スルトキハ

$$H_1 = \pm \frac{2E\theta \left( \frac{l}{2} + l_1 + l_2 + \frac{8f^2}{3l} + \frac{3h_1^2 + 16f_1^2}{3l_1} \right) t}{\text{Denominator eq. (13)}} \dots \dots \dots (22)$$







圖九 第十

(第一)中央扶構ノ撓度  
 今  $W_1$  ナル活荷重ト同時ニ補助荷重 (Auxiliary load)  $P$  ヲ中央扶構ノ中點ニ掛ケ是等ヨリ起ル内働ヲ計算シ之ヲ  $P$  ニ付テ微分シ最後ニ  $P=0$  ニ置ケハ Castigliano ノ第一定理ニヨリ中央扶構ノ中點ニ於ケル撓度ヲ見出し得ヘシ  
 $W_1$  ヨリ起ル鍊條ノ水平分力ヲ  $H$  トシ  $P$  ヨリ起ル鍊條ノ水平分力ヲ  $H_p$  トスレハ算式 (18) ニヨリ

$$H_p = \frac{5fl^2 P}{48I} \quad \text{Denominator eq. (12) or (13)}$$

$$K = \frac{5fl^2}{48I} \quad \text{Denominator eq. (12) or (13)}$$

ト置ケン  $H_p \parallel KP$  トナル又是等ノ荷重ノ爲メニ起ル水平每呎ノ吊材張力ヲ中央徑間及側徑間ニ於テ  $p$  及  $p_1$  トスレハ

$$p = \frac{8(H+KP)f}{l^2} \quad p_1 = \frac{8(H+KP)f_1}{l_1^2}$$

(一)扶構ノ内働ト其ノ微係數  
 左側扶構ノ彎曲率

$$M = \frac{1}{l} \left\{ W_1(a+a) - 4(H+KP)f_1 \right\} a + \frac{4(H+KP)f_1 a^2}{l^2}$$

$$\frac{\partial M}{\partial P} = \frac{4Kf_1}{l} \left( -a + \frac{a^2}{l} \right)$$

$$x > a \quad M = \frac{1}{l} \left\{ W(l-a) - 4(H+KP)f_1 \right\} x + \frac{4(H+KP)f_1}{l^2} x^2 - W_1(x-a)$$

$$\frac{dM}{dP} = \frac{4Kf_1}{l} \left( -x + \frac{x^2}{l} \right)$$

中央扶構ノ彎曲率

$$M = \frac{1}{l} \left\{ \frac{1}{2} Pl - 4(H+KP)f_1 \right\} x + \frac{4(H+KP)f_1}{l^2} x^2 \quad \frac{dM}{dP} = \frac{1}{l} \left( \frac{1}{2} l - 4Kf_1 \right) x + \frac{4Kf_1}{l^2} x^2$$

右側扶構ノ彎曲率

$$M = -\frac{4}{l_1} (H+KP)f_1 x + \frac{4(H+KP)f_1}{l_1^2} x^2 \quad \frac{dM}{dP} = \frac{4Kf_1}{l_1} \left( -x + \frac{x^2}{l_1} \right)$$

扶構ニ於ケル總内働ハ次ノ如シ

$$\omega = \int_0^a \frac{M^2}{2EI_1} dx + \int_a^{l_1} \frac{M^2}{2EI_1} dx + 2 \int_0^{x^2} \frac{M^2}{2EI} dx + \int_0^{l_1} \frac{M^2}{2EI_1} dx$$

$$\begin{aligned} \frac{d\omega}{dP} &= \int_0^a \frac{M}{EI_1} \left( \frac{dM}{dP} \right) dx + \int_a^{l_1} \frac{M}{EI_1} \left( \frac{dM}{dP} \right) dx + 2 \int_0^{x^2} \frac{M}{EI} \left( \frac{dM}{dP} \right) dx + \int_0^{l_1} \frac{M}{EI_1} \left( \frac{dM}{dP} \right) dx \\ &= \frac{Hf_1}{3EI} \left( 8Kf_1 - \frac{5}{16} l \right) + \frac{4HKf_1}{3EI} \left\{ \frac{4}{5} f_1^2 - \frac{W_1 a}{4H} \left( \frac{1}{l_1} - \frac{2x^2}{l_1} + \frac{x^3}{l_1^2} \right) \right\} \dots \dots \dots (a) \end{aligned}$$

(二) 鍊條ノ内働ト其ノ微係數

中央鍊條及側鍊條ノ張力ハ次ノ如シ

$$T = (H+KP) \left\{ 1 + \left( \frac{8f}{l^2} \right) x^2 \right\}^{\frac{1}{2}} \quad \frac{dT}{dP} = K \left\{ 1 + \left( \frac{8f}{l^2} \right) x^2 \right\}^{\frac{1}{2}}$$

1312

$$T_1 = (H + KP) \left\{ 1 + \left( \frac{l_1 + 4f_1}{l_1} - \frac{8f_1 x}{l_1^2} \right)^2 \right\}^{\frac{1}{2}} \quad \frac{dT_1}{dP} = K \left\{ 1 + \left( \frac{l_1 + 4f_1}{l_1} - \frac{8f_1 x}{l_1^2} \right)^2 \right\}^{\frac{1}{2}}$$

$$T_2 = (H + KP) \left\{ 1 + \left( \frac{l_1 - 4f_1}{l_1} \right)^2 \right\}^{\frac{1}{2}} \quad \frac{dT_2}{dP} = K \left\{ 1 + \left( \frac{l_1 - 4f_1}{l_1} \right)^2 \right\}^{\frac{1}{2}}$$

$$\omega = 2 \int_0^{\frac{l_1}{2}} \frac{T_1^2 ds}{2EA} + 2 \int_0^{l_1} \frac{T_1^2 ds}{2EA} + 2 \frac{T_2^2 l_2}{2EA}$$

$$\frac{d\omega}{dP} = 2 \int_0^{\frac{l_1}{2}} \frac{T_1}{EA} \left( \frac{dT_1}{dP} \right) ds + 2 \int_0^{l_1} \frac{T_1}{EA} \left( \frac{dT_1}{dP} \right) ds + 2 \frac{T_2}{EA} \left( \frac{dT_2}{dP} \right)$$

$$ds = \sqrt{1 + \left( \frac{dq}{dx} \right)^2} dx = \left\{ 1 + \left( \frac{8f_1}{l_1^2} x \right)^2 \right\}^{\frac{1}{2}} dx$$

$$ds = \sqrt{1 + \left( \frac{dq}{dx} \right)^2} dx = \left\{ 1 + \left( \frac{l_1 + 4f_1}{l_1} - \frac{8f_1 x}{l_1^2} \right)^2 \right\}^{\frac{1}{2}} dx$$

$$\frac{d\omega}{dP} = \frac{2HK}{EA} \int_0^{\frac{l_1}{2}} \left\{ 1 + \left( \frac{8f_1}{l_1^2} x \right)^2 \right\}^{\frac{3}{2}} dx + \frac{2HK}{EA} \int_0^{l_1} \left\{ 1 + \left( \frac{l_1 + 4f_1}{l_1} - \frac{8f_1 x}{l_1^2} \right)^2 \right\}^{\frac{3}{2}} dx$$

$$+ \frac{2HK}{EA} \left\{ 1 + \left( \frac{l_1 - 4f_1}{l_1} \right)^2 \right\}^{\frac{3}{2}} l_2$$

$$= \frac{2HK}{EA} \left( \frac{l_1}{2} + l_2 + \frac{4f_1^2}{l_1} + \frac{3l_1^2 + 16f_1^2}{2l_1} \right) \quad \text{nearby } \dots \dots \dots (5)$$

(三) 吊材ノ内働ト其ノ微係數

中央徑間及側徑間ニ於ケル吊材ノ張力ヲ  $S_1$  及  $S_2$  トスレバ

$$S_1 = p \left( \frac{l}{n} \right) = \frac{8(H+KP)f}{nl}$$

$$\frac{dS_1}{dP} = \frac{8Kf}{nl}$$

$$S_2 = p \left( \frac{l}{n_1} \right) = \frac{8(H+KP)f_1}{n_1 l_1}$$

$$\frac{dS_2}{dP} = \frac{8Kf_1}{n_1 l_1}$$

吊材ニ於ケル總内働ハ次ノ如シ

$$\omega = \frac{S_1^2 L_1}{2EA_1} + 2 \frac{S_2^2 L_2}{2EA_2}$$

$$\frac{d\omega}{dP} = \frac{S_1 L_1}{EA_1} \left( \frac{dS_1}{dP} \right) + 2 \frac{S_2 L_2}{EA_2} \left( \frac{dS_2}{dP} \right)$$

$$= \frac{64HK}{E} \left\{ \frac{f^2}{A_1 n^2} \left( h - \frac{2}{3} f \right) + \frac{2f_1^2}{A_1 n_1^2} \left( h - \frac{h_1}{2} - \frac{2}{3} f_1 \right) \right\} \dots \dots \dots (c)$$

(四) 塔ノ内働ト其ノ微係數  
塔ノ受クル全應力ハ次ノ如シ

$$S = (H+KP) \left( \frac{4f}{l} + \frac{h_1+4f_1}{l_1} \right) \quad \frac{dS}{dP} = K \left( \frac{4f}{l} + \frac{h_1+4f_1}{l_1} \right)$$

$$\omega = 2 \frac{S^2 l_2}{2EA^2}$$

$$\frac{d\omega}{dP} = 2 \frac{S l_2}{EA_s} \left( \frac{dS}{dP} \right) = \frac{2HK}{EA_s} \left( \frac{4f}{l} + \frac{h_1+4f_1}{l_1} \right)^2 l_2 \dots \dots \dots (d)$$

(五) 中央扶構ノ撓度ノ決定

Castiglianoノ第一定理ニヨリ中央扶構ノ中點ニ於ケル撓度 $\delta$ ハ次ノ如シ

$$\delta = \frac{\partial \omega}{\partial P} = \text{Equation (a)} + \text{Equation (b)} + \text{Equation (c)} + \text{Equation (d)}$$

上ノ方程式ヨリ次ノ結果ヲ得ヘシ

$$\begin{aligned} \delta = \frac{H}{E} & \left[ \frac{fl^2}{3I} \left( \frac{8}{5} Kf - \frac{5}{16} l \right) + \frac{4Kf_1}{3I} \left\{ \frac{4}{5} fl_1 - \frac{W_1 a}{4H} \left( l_1 - \frac{2a^2}{l_1} + \frac{a^3}{l_1^2} \right) \right\} \right. \\ & + \frac{2K}{A} \left( \frac{l}{2} + l_1 + l_2 + \frac{4f^2}{l} + \frac{3l_1^2 + 16f_1^2}{2l_1} \right) \\ & + 64K \left\{ \frac{f^2}{A_1^2 l^2} \left( h - \frac{2}{3} f \right) + \frac{2f_1^2}{A_2^2 l_1^2} \left( h - \frac{l_1}{2} - \frac{2}{3} f_1 \right) \right\} + \frac{2K}{A_3} \left( \frac{4f}{l} + \frac{l_1 + 4f_1}{l_1} \right)^2 l_2 \dots \dots (23) \end{aligned}$$

吊材及塔ノ變形ヨリ來タル影響ヲ省略スルトキハ(4<sub>1</sub> 4<sub>2</sub> 4<sub>3</sub>ヲ含ム項ヲ省ケン宜シ)

$$\begin{aligned} \delta = \frac{H}{E} & \left[ \frac{fl^2}{3I} \left( \frac{8}{5} Kf - \frac{5}{16} l \right) + \frac{4Kf_1}{3I} \left\{ \frac{4}{5} fl_1 - \frac{W_1 a}{4H} \left( l_1 - \frac{2a^2}{l_1} + \frac{a^3}{l_1^2} \right) \right\} \right. \\ & + \frac{2K}{A} \left( \frac{l}{2} + l_1 + l_2 + \frac{4f^2}{l} + \frac{3l_1^2 + 16f_1^2}{2l_1} \right) \dots \dots (24) \end{aligned}$$

撓度ニ對シ吊材及塔ノ變形ヨリ來ル影響ハ頗ル小ナルヲ以テ今後ハ常ニ之ヲ省略スルモノトス  
 Wナル等布荷重カ $\omega$ マテ乘リシトキニハ(前式ニ於テ $W_1$ ノ代リニ $\omega da$ ヲ入レ $a$ ノ代リニ $\omega$ ヲ置キ  
 0ヨリ $\omega_1$ マテ積分スレハ宜シ)

$$\begin{aligned} \delta = \frac{H}{E} & \left[ \frac{fl}{3I} \left( \frac{8}{5} Kf - \frac{5}{16} l \right) + \frac{4Kf_1}{3I} \left\{ \frac{4}{5} fl_1 - \frac{\omega da^2}{4H} \left( \frac{l_1}{2} - \frac{a_1^2}{2l_1} + \frac{a_1^3}{5l_1^2} \right) \right\} \right. \\ & + \frac{2K}{A} \left( \frac{l}{2} + l_1 + l_2 + \frac{4f^2}{l} + \frac{3l_1^2 + 16f_1^2}{2l_1} \right) \dots \dots (25) \end{aligned}$$

同様ニシテ $W_2$ ニ對スル中央扶構ノ撓度ヲ求ムレハ次ノ如シ

$$\delta = \frac{H}{E} \left[ \frac{16Kf_1^2 l_1}{15I} + \frac{fl}{3I} \left( \frac{8}{5} Kf - \frac{5}{16} l \right) + \frac{W_2^2}{HI} \left( \frac{l^2}{16} - \frac{l^2}{12} \right) - \frac{Kf}{3I} \left( l^2 - 2l^2 + \frac{l^3}{l} \right) \right]$$

$$+ \frac{2K}{A} \left( \frac{l}{2} + l_1 + l_2 + \frac{4f^2}{l} + \frac{3h_1^2 + 16f_1^2}{2l} \right) \dots \dots \dots (26)$$

茲ニ注意ヲ要スルハ、 $W_2$  ナル荷重ニ於テ左端支承ヨリ計レル  $b$  カ  $l/2$  ヨリ大ナル時ハ  $b$  ハ右端支承ヨリ之ヲ計ラサルヘカラス  
 $w$  ナル等布荷重カ  $b$  マテ乘リシ時ニハ

$$\delta = \frac{H}{E} \left[ \frac{16Kf_1^2 l}{15l_1} + \frac{fl}{3l} \left( \frac{8}{5} Kf - \frac{5}{16} l \right) + \frac{2bh_1^2}{HI} \left( \frac{l^2}{32} - \frac{b_1^2}{48} \right) \right. \\ \left. - \frac{Kf}{3l} \left( \frac{l^2}{2} - \frac{b^2}{2} + \frac{b_1^2}{5l} \right) \right] + \frac{2K}{A} \left( \frac{l}{2} + l_1 + l_2 + \frac{4f^2}{l} + \frac{3h_1^2 + 16f_1^2}{2l} \right) \dots \dots \dots (27)$$

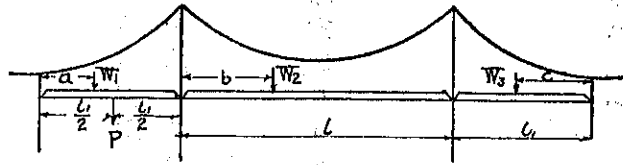
又等布荷重ニ於テ左端支承ヨリ計レル  $b$  カ  $l/2$  ヨリ大ナル時ハ先ツ  $l$  ナル徑間ノ滿載荷重ニ對スル撓度ヲ求メ其レヨリ  $l/2$  ナル部分カ荷重ヲ受ケシ際ニ起ル撓度ヲ求メ之ヲ減スレハ宜シ  
 (第二) 側扶構ノ撓度

此ノ場合ニモ補助荷重  $P$  ヲ側扶構ノ中點ニ掛ケ  $P$  ノ爲メニ起レル鏢條ノ水平分力ヲ  $H_p$  トスレハ算式 (12) ニヨリ

$$H_p = \frac{b f l_1^2 P}{48 I} \quad \text{Denominator eq. (12) or (13)}$$

$$K = \frac{5 f l_1^2}{48 I} \quad \text{Denominator eq. (12) or (13)}$$

トスレハ  $H_p = K P$  トナル  $W_1$  ノ爲メニ起ル側扶構ノ撓度ハ次ノ如シ



第 二 十 二 圖

茲ニ注意ヲ要スルハ \$W\_1\$ ナル荷重ニ於テ左端支承ヨリ計レルカ \$l/2\$ ヨリ大ナル時ハ \$a\$ ハ右端支承ヨリ之ヲ計ラサルヘカラス  
 \$W\$ ナル等布荷重カ \$a\_1\$ マテ乘リシ時ニハ

$$\delta = \frac{H}{E} \left[ \frac{8Kf^2}{15I} + \frac{f_1^2}{3I} \left( \frac{16}{5} Kf_1 - \frac{5}{16} l_1 \right) + \frac{wa_1^2}{H_1} \left( \left( \frac{l_1^2}{32} - \frac{a_1^2}{48} \right) - \frac{Kf_1}{3I} \left( \frac{l_1^2}{2} - \frac{a_1^2}{2} + \frac{a_1^3}{5I} \right) \right) \right. \\ \left. + \frac{2K}{A} \left( \frac{l}{2} + l_1 + l_2 + \frac{4f}{l} + \frac{3l_1^2 + 16f_1^2}{2I} \right) \right] \dots \dots \dots (29)$$

又等布荷重ニ於テ左端支承ヨリ計レル \$a\_1\$ カ \$l/2\$ ヨリ大ナル時ハ先ツ \$l\$ ナル徑  
 間ノ滿載荷重ニ對スル撓度ヲ求メ其レヨリ \$l\_1 - a\_1\$ ナル部分カ荷重ヲ受ケシ際  
 \$W\_2\$ ノ爲メニ起ル撓度ハ次ノ如シ

$$\delta = \frac{H}{E} \left[ \frac{f_1^2}{3I} \left( \frac{16}{5} Kf_1 - \frac{5}{16} l_1 \right) + \frac{4Kf}{3I} \left\{ \frac{2}{5} fl - \frac{W_2 b}{4H} \left( l - \frac{2b^2}{l} + \frac{b^3}{r} \right) \right\} \right. \\ \left. + \frac{2K}{A} \left( \frac{l}{2} + l_1 + l_2 + \frac{4f}{l} + \frac{3l_1^2 + 16f_1^2}{2I} \right) \right] \dots \dots \dots (30)$$



10 ナル等布荷重カハマテ乘リシキニ

$$\delta = \frac{H}{E} \left[ \frac{f_1^2}{3l} \left( \frac{16}{5} Kf_1 - \frac{5}{16} l_1 \right) + \frac{4Kf_1}{3l} \left( \frac{2}{5} fl - \frac{wb_1^2}{4H} \left( \frac{l}{2} - \frac{b_1^2}{2l} + \frac{b_1^3}{5f^2} \right) \right) + \frac{2K}{4} \left( \frac{l}{2} + l_1 + l_2 + \frac{4f^2}{l} + \frac{3b_1^2 + 16f_1^2}{2l} \right) \right] \dots \dots \dots (31)$$

W<sub>3</sub> ノタメニ起ル撓度ハ次ノ如シ

$$\delta = \frac{H}{E} \left[ \frac{8Kf_1^2}{15l} + \frac{f_1^2}{3l} \left( \frac{16}{5} Kf_1 - \frac{5}{16} l_1 - \frac{W_3 Kc}{Hl} \left( l_1 - \frac{2c^2}{l} + \frac{c^3}{l_1^2} \right) \right) + \frac{2K}{4} \left( \frac{l}{2} + l_1 + l_2 + \frac{4f^2}{l} + \frac{3b_1^2 + 16f_1^2}{2l} \right) \right] \dots \dots \dots (32)$$

10 ナル等布荷重カハマテ乘リシ時ニ

$$\delta = \frac{H}{E} \left[ \frac{8Kf_1^2}{15l} + \frac{f_1^2}{3l} \left( \frac{16}{5} Kf_1 - \frac{5}{16} l_1 - \frac{wKc_1^2}{Hl_1} \left( \frac{l}{2} - \frac{c_1^2}{2l} + \frac{c_1^3}{5l_1^2} \right) \right) + \frac{2K}{4} \left( \frac{l}{2} + l_1 + l_2 + \frac{4f^2}{l} + \frac{3b_1^2 + 16f_1^2}{2l} \right) \right] \dots \dots \dots (33)$$

第九章 温度ノ變化ノ爲メニ受クル扶構ノ撓度

(第一) 中央扶構ノ撓度

今中央扶構ノ中點ニ P ナル補助荷重ヲ掛ケタリトシ又温度カ正規温度ヨリ P 丈ケ變化シタリト假定ス

温度ノ變化ヨリ起ル撓條ノ水平分力ヲ H<sub>1</sub> トシ P ヨリ起ル撓條ノ水平分力ヲ H<sub>2</sub> トスレハ

$$H_1 = \frac{5f^2 P}{4SI} \dots \dots \dots = KP$$

又中央徑間及側徑間ニ於ケル水平每呎ノ吊材張力ヲ  $p$  及  $p_1$  トスレハ

$$p = \frac{8(H_c + KP)f}{l^2} \quad p_1 = \frac{8(H_c + KP)f_1}{l_1^2}$$

(一) 扶構ノ内働ト其ノ微係數

兩側扶構ノ彎曲率

$$M = -\frac{4}{l_1}(H_c + KP)f_1\omega + \frac{4(H_c + KP)f_1}{l_1^2}\omega^2 \quad \frac{dM}{dP} = \frac{4Kf_1}{l_1}\left(-\alpha + \frac{\omega^2}{l_1}\right)$$

中央扶構ノ彎曲率

$$M = \frac{1}{l}\left\{\frac{1}{2}Pl - 4(H_c + KP)f\right\}\omega + \frac{4(H_c + KP)f}{l^2}\omega^2$$

$$\frac{dM}{dP} = \frac{1}{l}\left\{\left(\frac{1}{2}l - 4Kf\right)\omega + \frac{4Kf}{l}\omega^2\right\}$$

$$\omega = 2\int_0^{l_1} \frac{M^2}{2EI_1} dx + 2\int_0^{\frac{l}{2}} \frac{M^2}{2EI} dx$$

$$\frac{d\omega}{dP} = 2\int_0^{l_1} \frac{M}{EI_1} \left(\frac{dM}{dP}\right) dx + 2\int_0^{\frac{l}{2}} \frac{M}{EI} \left(\frac{dM}{dP}\right) dx = \frac{16H_c K f_1^2 l_1}{15EI_1} + \frac{H_c f l}{3EI} \left(\frac{8Kf}{5} - \frac{5}{16}l\right)$$

(二) 鐵條ノ内働ト其ノ微係數

$$T = (H_c + KP)\left\{1 + \left(\frac{8f}{l}\right)^2\omega^2\right\}^{\frac{1}{2}} \quad \frac{dT}{dP} = K\left\{1 + \left(\frac{8f}{l}\right)^2\omega^2\right\}^{\frac{1}{2}}$$

$$0 = 2 \int_0^{\frac{l}{2}} \frac{T_1^2 ds}{2EA} + 2 \int_0^{l_1} \frac{T_1^2 ds}{2EA} + 2 \int_0^{l_2} \frac{T_1^2 ds}{2EA} - 2 \int_0^{\frac{l}{2}} T_1 \theta ds - 2 \int_0^{l_1} T_1 \theta ds - 2 \int_0^{l_2} T_1 \theta ds$$

$$\frac{d\omega}{dP} = 2 \int_0^{\frac{l}{2}} \frac{T}{EA} \left( \frac{dT}{dP} \right) ds + 2 \int_0^{l_1} \frac{T_1}{EA} \left( \frac{dT_1}{dP} \right) ds + 2 \int_0^{l_2} \frac{T_2}{EA} \left( \frac{dT_2}{dP} \right) ds$$

$$- 2 \int_0^{\frac{l}{2}} \left( \frac{dT}{dP} \right) (\theta ds) - 2 \int_0^{l_1} \left( \frac{dT_1}{dP} \right) (\theta ds) - 2 \left( \frac{dT_2}{dP} \right) \theta l_2$$

$$= \frac{2H_1 K}{EA} \left( \frac{l}{2} + l_1 + l_2 + \frac{4f^2}{l} + \frac{3h_1^2 + 16f_1^2}{2l_1} \right)$$

$$- 2K\theta \left( \frac{l}{2} + l_1 + l_2 + \frac{8f^2}{3l} + \frac{3h_1^2 + 16f_1^2}{3l_1} \right)$$

(三) 吊材ノ内働ト其ノ微係數

中央徑間及側徑間ニ於ケル吊材ノ張力ヲ  $S_1$  及  $S_2$  トスベシ

$$S_1 = \frac{8(H_1 + KP) f}{n l} \qquad \frac{dS_1}{dP} = \frac{8Kf}{n l}$$

$$S_2 = \frac{8(H_2 + KP) f_1}{n_1 l_1} \qquad \frac{dS_2}{dP} = \frac{8Kf_1}{n_1 l_1}$$

$$\omega = \frac{S_1^2 L_1}{2EA_1} + 2 \frac{S_2^2 L_2}{2EA_2} - S_1(\theta_1 L_1) - 2S_2(\theta_2 L_2)$$

$$\begin{aligned} \frac{d\omega}{dP} &= \frac{S_1 L_1}{EA_1} \left( \frac{dS_1}{dP} \right) + 2 \frac{S_2 L_2}{EA_2} \left( \frac{dS_2}{dP} \right) - (\theta_1 L_1) - 2 \left( \frac{dS_2}{dP} \right) \theta_2 L_2 \\ &= \frac{64 H_c K f^2}{EA_1 \omega^2} \left( h - \frac{2}{3} f \right) + \frac{128 H_c K f_1^2}{EA_2 \omega^2 L_1^2} \left( h - \frac{1}{2} l_1 - \frac{2}{3} f_1 \right) \\ &\quad - 8 K \theta_2 \left\{ \frac{f}{l} \left( h - \frac{2}{3} f \right) + \frac{2 f_1}{l} \left( h - \frac{1}{2} l_1 - \frac{2}{3} f_1 \right) \right\} \end{aligned}$$

(四) 塔ノ内働ト其ノ微係數

$$S = (H_c + KP) \left( \frac{4f}{l} + \frac{h_1 + 4f_1}{l} \right) \quad \frac{dS}{dP} = K \left( \frac{4f}{l} + \frac{h_1 + 4f_1}{l} \right)$$

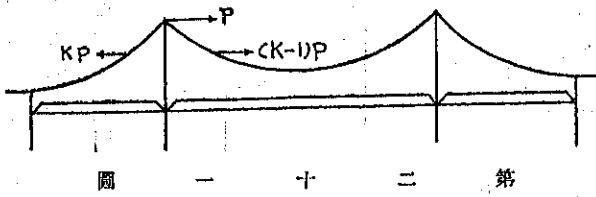
$$\omega = 2 \frac{S^2 h_2}{2EA_3} + 2S(\theta_1 l_2)$$

$$\begin{aligned} \frac{d\omega}{dP} &= 2 \frac{S h_2}{EA_3} \left( \frac{dS}{dP} \right) + 2 \left( \frac{dS}{dP} \right) \theta_1 l_2 \\ &= \frac{2 H_c K}{EA_3} \left( \frac{4f}{l} + \frac{h_1 + 4f_1}{l} \right)^2 h_2 + 2 K \theta_1 \left( \frac{4f}{l} + \frac{h_1 + 4f_1}{l} \right) h_2 \end{aligned}$$

(五) 中央扶橋ノ撓度ノ決定

温度ノ變化ノ爲メニ起ル中央扶橋ノ中點ノ撓度  $\delta_c$  ハ次ノ如シ

$$\begin{aligned} \delta_c &= \frac{2 H_c}{E} \left[ \frac{8 K f_1^2 l_1}{15 L_1} + \frac{f l}{6 I} \left( \frac{8 K f}{5} - \frac{5 l}{16} \right) + \frac{K}{A} \left( \frac{l}{2} + l_1 + l_2 + \frac{4 f^2}{l} + \frac{3 l_1^2 + 16 f_1^2}{2 l} \right) \right. \\ &\quad \left. + 32 K \left\{ \frac{f^2}{A_1 \omega^2} \left( h - \frac{2}{3} f \right) + \frac{2 f_1^2}{A_2 \omega^2 L_1^2} \left( h - \frac{1}{2} l_1 - \frac{2}{3} f_1 \right) \right\} + \frac{K}{A_3} \left( \frac{4f}{l} + \frac{h_1 + 4f_1}{l} \right)^2 h_2 \right] \end{aligned}$$



第 二 十 一 圖

吊材及塔ノ影響ヲ省略スルトキハ

$$-2KH \left[ \frac{l}{2} + l_1 + l_2 + \frac{8f^2}{3l} + \frac{3h_1^2 + 16f_1^2}{3l_1} \right] + 4 \left[ \frac{f}{l} \left( h - \frac{2}{3}f \right) + \frac{2f_1}{l_1} \left( h - \frac{l_2}{2} - \frac{2}{3}f_1 \right) \right] - \left( \frac{4f}{l} + \frac{l_2 + 4f_1}{l_1} \right) h_2 \quad \dots \dots \dots (34)$$

$$\delta_0 = \frac{2H_0}{E} \left[ \frac{8Kf_1^2 l_1}{15l} + \frac{fl}{6l} \left( \frac{8}{5}Kf - \frac{5}{16}l \right) + \frac{K}{A} \left( \frac{l}{2} + l_1 + l_2 + \frac{4f^2}{l} + \frac{3h_1^2 + 16f_1^2}{2l} \right) \right] - \frac{2KH \left( \frac{l}{2} + l_1 + l_2 + \frac{8f^2}{3l} + \frac{3h_1^2 + 16f_1^2}{3l} \right)}{\dots \dots \dots} \quad \dots \dots \dots (35)$$

(第二)側扶構ノ撓度

前同様側扶構ノ中點ニPナル補助荷重ヲ掛ケタリトシPノ爲メニ起ル鍊條ノ水平分力ヲH<sub>y</sub>トスルハ

$$H_y = \frac{5fl_1^2}{48l} P \quad \text{Denominator eq. (12) or (13)} = KP$$

温度ノ變化ノ爲メ側扶構ノ中點ニ起ル撓度ハ吊材及ヒ塔ノ影響ヲ略スル時ハ次ノ如シ

$$\delta_1 = \frac{2H_1}{E} \left[ \frac{4Kf^2 l}{15l} + \frac{fl_1}{6l} \left( \frac{16}{5}Kf_1 - \frac{5}{16}l_1 \right) + \frac{K}{A} \left( \frac{l}{2} + l_1 + l_2 + \frac{4f^2}{l} + \frac{3h_1^2 + 16f_1^2}{2l} \right) \right] - \frac{2KH \left( \frac{l}{2} + l_1 + l_2 + \frac{8f^2}{3l} + \frac{3h_1^2 + 16f_1^2}{3l} \right)}{\dots \dots \dots} \quad \dots \dots \dots (36)$$

第十章 活荷重ノ爲メニ受クル支鞍(Saddle)ノ塔上ニ於ケル水平移動

今左ノ塔ノ頂上ニ於テ水平ノ方向ニPナル補助荷重ヲ掛ケタリトシPノ爲メニ起リシ鍊條應力ノ水平分力ヲ左側鍊條ニテ $KP$ トシ中央鍊條及右側鍊條ニテ $(K-1)P$ トスレハCastiglianoノ第二定理ノ應用ニヨリ次ノ如キ $K$ ノ値ヲ得ヘシ

$$K = \frac{\left[ \frac{8}{15} \left( \frac{f^2}{I} + \frac{f^2 l_1}{I} \right) + \frac{1}{A} \left( l + l_1 + l_2 + \frac{8f^2}{l} + \frac{3l_1^2 + 16f_1^2}{2l} \right) + 64 \left\{ \frac{f^2}{4n^2 E} \left( n - \frac{2}{3} f \right) + \frac{f_1^2}{4n_1 l_1^2} \left( l - \frac{l_1}{2} - \frac{2}{3} f_1 \right) \right\} + \frac{l_2}{A_2} \left( \frac{4f}{l} + \frac{l_1 + 4f_1}{l} \right) \right] \left( \frac{8f}{l} + \frac{l_1 + 4f_1}{l} \right)}{\text{Denominator eq. (12)}}$$

吊材及塔ノ影響ヲ省略スル時ハ

$$K = \frac{\frac{8}{15} \left( \frac{f^2}{I} + \frac{f_1^2}{I} \right) + \frac{1}{A} \left( l + l_1 + l_2 + \frac{8f^2}{l} + \frac{3l_1^2 + 16f_1^2}{2l} \right)}{\text{Denominator eq. (13)}} \dots \dots (38)$$

算式(37)(38)ニ於テ $K$ ノ値ハ殆ト一(one)ニ等シキヲ以テPナル補助荷重ノ爲メニ起ル鍊條ノ水平分力ヲ左側鍊條ニテPトシ中央鍊條及右側鍊條ニテ0ト假定スルモ大差ナシ

次ニ $W_1$ ノ爲メニ起ル支鞍ノ移動ヲ見出サントス

今 $W_1$ ト共ニ補助荷重Pヲ塔ノ頂上ニ於テ水平ノ方向ニ掛クレハ水平毎呎ノ吊

材張力ハ次ノ如シ  
但シ $W_1$ ヨリ起リシ鍊條ノ水平分力ヲ $H$ トス

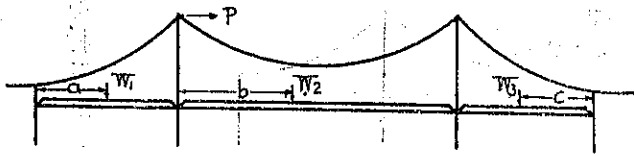


圖 二 十 二 第

$$p_1 = \frac{8(H+P)f_1}{l_1^2} \quad \text{for left span}$$

$$p = \frac{8Hf}{l^2} \quad \text{for center span}$$

$$p_2 = \frac{8Hf_1}{l_1^2} \quad \text{for right span}$$

左側扶構ノ彎曲率  
(一) 扶構ノ内働ト其ノ微係數

$$x < a \quad M = \frac{1}{l_1} \left\{ W_1(l_1 - a) - 4(H+P)f_1 \right\} x + \frac{4(H+P)f_1}{l_1^2} x^2$$

$$\frac{dM}{dP} = \frac{4f_1}{l_1} \left( -x + \frac{x^2}{l_1} \right)$$

$$x > a \quad M = \frac{1}{l_1} \left\{ W_1(l_1 - a) - 4(H+P)f_1 \right\} x + \frac{4(H+P)f_1}{l_1^2} x^2 - W_1(x - a)$$

$$\frac{dM}{dP} = \frac{4f_1}{l_1} \left( -x + \frac{x^2}{l_1} \right)$$

中央扶構ノ彎曲率

$$M = -\frac{4Hf}{l} x + \frac{4Hf}{l^2} x^2 \quad \frac{dM}{dP} = 0$$

右側扶構ノ彎曲率

$$M = -\frac{4Hf_1}{l_1} x + \frac{4Hf_1}{l_1^2} x^2 \quad \frac{dM}{dP} = 0$$

論 說 三徑間ニシテ單扶橋ヲ有スル吊橋ノ略理論

FIG

$$\begin{aligned} \omega &= \int_0^a \frac{M^2}{2EI} dx + \int_a^{l_1} \frac{M^2}{2EI} dx + \int_0^l \frac{M^2}{2EI} dx + \int_0^{l_1} \frac{M^2}{2EI} dx \\ \frac{d\omega}{dP} &= \int_0^a \frac{M}{EI} \left( \frac{dM}{dP} \right) dx + \int_a^{l_1} \frac{M}{EI} \left( \frac{dM}{dP} \right) dx + \int_0^l \frac{M}{EI} \left( \frac{dM}{dP} \right) dx + \int_0^{l_1} \frac{M}{EI} \left( \frac{dM}{dP} \right) dx \\ &= \frac{Hf}{3EI} \left\{ \frac{8f l_1}{5} - \frac{W_1 a}{H} \left( l_1 - \frac{2a^2}{l_1} + \frac{a^3}{l_1^2} \right) \right\} \end{aligned}$$

(1) 懸條ノ内働ニ其ノ微係數

left span

$$\left\{ \begin{aligned} T_1 &= (H+P) \left\{ 1 + \left( \frac{h_1 + 4f_1}{l_1} - \frac{8f_1}{l_1^2} a \right)^2 \right\}^{\frac{1}{2}} \\ \frac{dT_1}{dP} &= \left\{ 1 + \left( \frac{h_1 + 4f_1}{l_1} - \frac{8f_1}{l_1^2} a \right)^2 \right\}^{\frac{1}{2}} \\ T_2 &= (H+P) \left\{ 1 + \left( \frac{h_1 - 4f_1}{l_1} \right)^2 \right\}^{\frac{1}{2}} \\ \frac{dT_2}{dP} &= \left\{ 1 + \left( \frac{h_1 - 4f_1}{l_1} \right)^2 \right\}^{\frac{1}{2}} \end{aligned} \right.$$

center span

$$T = H \left\{ 1 + \left( \frac{8f}{l} \right)^2 a^2 \right\}^{\frac{1}{2}} \quad \frac{dT}{dP} = 0$$

right span

$$\left\{ \begin{aligned} T_1 &= H \left\{ 1 + \left( \frac{h_1 + 4f_1}{l_1} - \frac{8f_1}{l_1^2} a \right)^2 \right\}^{\frac{1}{2}} \\ \frac{dT_1}{dP} &= 0 \\ T_2 &= H \left\{ 1 + \left( \frac{h_1 - 4f_1}{l_1} \right)^2 \right\}^{\frac{1}{2}} \\ \frac{dT_2}{dP} &= 0 \end{aligned} \right.$$

$$\omega = \int_0^{l_1} \frac{T_1^2 ds}{2EA} + \frac{T_2^2 l_2}{2EA} + 2 \int_0^{\frac{l}{2}} \frac{T^2 ds}{2EA} + \int_0^{l_1} \frac{T_1^2 ds}{2EA} + \frac{T_2^2 l_2}{2EA}$$



$$\begin{aligned} \frac{d\omega}{dP} &= \int_0^{l_1} \frac{T_1}{EA} \left( \frac{dT_1}{dP} \right) ds + \frac{T_2}{EA} \left( \frac{dT_2}{dP} \right) + 2 \int_0^{l_2} \frac{T}{EA} \left( \frac{dT}{dP} \right) ds \\ &\quad + \int_0^{l_1} \frac{T_1}{EA} \left( \frac{dT_1}{dP} \right) ds + \frac{T_2^2}{EA} \left( \frac{dT_2}{dP} \right) \\ &= \frac{H}{EA} \left( l_1 + l_2 + \frac{3h_2^2 + 16f_1^2}{2l_1} \right) \quad \text{nearly} \end{aligned}$$

(三) 吊材の反働 + 其の微係數

$$\text{Left span} \quad S_2 = \frac{8(H+P)f_1}{n_1 l_1} \quad \frac{dS_2}{dP} = \frac{8f_1}{n_1 l_1}$$

$$\text{Center span} \quad S_1 = \frac{8Hf}{n l} \quad \frac{dS_1}{dP} = 0$$

$$\text{Right span} \quad S_2 = \frac{8Hf_1}{n_1 l_1} \quad \frac{dS_2}{dP} = 0$$

$$\frac{d\omega}{dP} = \frac{S_2 L_2}{EA_2} \left( \frac{dS_2}{dP} \right) + \frac{S_1 L_1}{EA_1} \left( \frac{dS_1}{dP} \right) + \frac{S_1 L_2}{EA_2} \left( \frac{dS_2}{dP} \right) = \frac{64Hf_1^2}{EA_2 n_1 l_1^2} \left( h - \frac{h_1}{2} - \frac{2}{3} f_1 \right)$$

(四) 塔の内働 + 其の微係數

$$\text{Left tower} \quad S = H \frac{4f}{l} + (H+P) \frac{h_1 + 4f_1}{l_1} \quad \frac{dS}{dP} = \frac{h_1 + 4f_1}{l_1}$$

$$\text{Right tower} \quad S = H \left( \frac{4f}{l} + \frac{h_1 + 4f_1}{l_1} \right) \quad \frac{dS}{dP} = 0$$

$$\frac{d\omega}{dP} = \frac{S h_2}{EA_3} \left( \frac{dS}{dP} \right) + \frac{S h_2}{EA_3} \left( \frac{dS}{dP} \right)$$

W<sub>1</sub>ノタメニ起ル支鞍ノ水平移動Δ<sub>1</sub>ノ次ノ如シ  
 (五) 支鞍ノ水平移動ノ決定

$$= \frac{H}{EA_3} \left( \frac{4f_1}{l} + \frac{l_1+4f_1}{l} \right) \left( \frac{l_1+4f_1}{l} \right) l_2$$

$$\begin{aligned} \Delta l = \frac{H}{E} & \left[ \frac{f_1}{3I} \left\{ 8f_1 l_1 - \frac{W_1 a}{H} \left( l_1 - \frac{2a^2}{l} + \frac{a^2}{l^2} \right) \right\} + \frac{1}{A} \left( l_1 + l_2 + \frac{3h_1^2 + 16f_1^2}{2l_1} \right) \right. \\ & \left. + \frac{64f_1^2}{A_2 a^2 l^2} \left( l_1 - \frac{h_1}{2} - \frac{2}{3} f_1 \right) + \frac{h_2}{A_3} \left( \frac{4f_1}{l} + \frac{h_1 + 4f_1}{l_1} \right) \left( \frac{l_1 + 4f_1}{l_1} \right) \right] \dots \dots \dots (39) \end{aligned}$$

吊材及塔ノ影響ヲ省略スルトキハ

$$\Delta l = \frac{H}{E} \left[ \frac{f_1}{3I} \left\{ 8f_1 l_1 - \frac{W_1 a}{H} \left( l_1 - \frac{2a^2}{l} + \frac{a^2}{l^2} \right) \right\} + \frac{1}{A} \left( l_1 + l_2 + \frac{3h_1^2 + 16f_1^2}{2l_1} \right) \right] \dots \dots \dots (40)$$

支鞍ノ移動ニ對スル吊材及塔ノ影響ハ頗ル小ナルヲ以テ今後ハ之ヲ略ス  
 Wナル等布荷重カハマテ乘リシ時ハ

$$\Delta l = \frac{H}{E} \left[ \frac{f_1}{3I} \left\{ 8f_1 l_1 - \frac{w a a^2}{H} \left( l_1 - \frac{a_1^2}{2} + \frac{a_2^2}{5l^2} \right) \right\} + \frac{1}{A} \left( l_1 + l_2 + \frac{3h_1^2 + 16f_1^2}{2l_1} \right) \right] \dots \dots \dots (41)$$

同様ニシテW<sub>2</sub>ノ爲メニ起ル支鞍ノ移動ヲ求ムヘン次ノ如シ

$$\Delta l = \frac{H}{E} \left[ \frac{8f_1^2 l_1}{15I} + \frac{1}{A} \left( l_1 + l_2 + \frac{3h_1^2 + 16f_1^2}{2l_1} \right) \right] \dots \dots \dots (42)$$

等布荷重カハマテ乘リシ時ニモ算式(42)ハ其ノ儘之ヲ適用スル事ヲ得ヘシ  
 又W<sub>3</sub>ノ爲メニ起ル支鞍ノ移動ハ次ノ如シ

$$\Delta l = \frac{H}{E} \left[ \frac{8f_1^2 l_1}{15I} + \frac{1}{A} \left( l_1 + l_2 + \frac{3h_1^2 + 16f_1^2}{2l_1} \right) \right] \dots \dots \dots (43)$$

等布荷重カ $\rho$ マテ乘リシ時ニモ算式(43)ノ其ノ儘之ヲ適用スル事ヲ得ヘシ

第十一章 温度ノ變化ノ爲メニ受クル支較ノ水平移動

前同様左ノ塔ノ頂上ニ於テ水平ノ方向ニPナル補助荷重ヲ掛ケPノ爲メニ起リシ左側鍊條ノ水平分力ヲPトシ温度ノ變化ノ爲メニ起リシ鍊條ノ水平分力ヲHトス

(一) 扶構ノ内働ト其ノ微係數

左側扶構ノ彎曲率

$$M = -\frac{4(H_c + P)f_1}{l_1} \alpha + \frac{4(H_c + P)f_1}{l_1^2} \alpha^2 \quad \frac{dM}{dP} = \frac{4f_1}{l_1} \left( -\alpha + \frac{\alpha^2}{l_1} \right)$$

$$\frac{d\omega}{dP} = \int_0^{l_1} \frac{M}{EI} \left( \frac{dM}{dP} \right) dx = \frac{8Hf_1^2 l_1}{15EI}$$

(二) 鍊條ノ内働ト其ノ微係數

左側徑間ニ於ケル鍊條ノ應力ハ次ノ如シ

$$T_1 = (H_c + P) \left\{ 1 + \left( \frac{l_1 + 4f_1}{l_1} - \frac{8f_1}{l_1^2} \alpha \right)^2 \right\}^{\frac{1}{2}} \quad \frac{dT_1}{dP} = \left\{ 1 + \left( \frac{l_1 + 4f_1}{l_1} - \frac{8f_1}{l_1^2} \alpha \right)^2 \right\}^{\frac{1}{2}}$$

$$T_2 = (H_c + P) \left\{ 1 + \left( \frac{l_1 - 4f_1}{l_1} \right)^2 \right\}^{\frac{1}{2}} \quad \frac{dT_2}{dP} = \left\{ 1 + \left( \frac{l_1 - 4f_1}{l_1} \right)^2 \right\}^{\frac{1}{2}}$$

$$\begin{aligned} \frac{d\omega}{dP} &= \int_0^{l_1} \frac{T_1}{EA} \left( \frac{dT_1}{dP} \right) ds + \frac{T_2 l_2}{EA} \left( \frac{dT_2}{dP} \right) - \int_0^{l_1} \left( \frac{dT_1}{dP} \right) \theta t ds - \left( \frac{dT_2}{dP} \right) \theta t l_2 \\ &= \frac{H_c}{EA} \left( l_1 + l_2 + \frac{3h_1^2 + 16f_1^2}{2l_1} \right) - \theta t \left( l_1 + l_2 + \frac{3h_1^2 + 16f_1^2}{3l_1} \right) \quad \text{nearby} \end{aligned}$$

(三) 吊材ノ内働ト其ノ微係數

左側徑間ニ於ケル吊材ノ應力ハ次ノ如シ

$$S_2 = \frac{8(H_2 + P)f_1}{7h_1} \quad \frac{dS_2}{dP} = \frac{8f_1}{7h_1}$$

$$\begin{aligned} \frac{d\omega}{dP} &= \frac{S_2 L_2}{EA_2} \left( \frac{dS_2}{dP} \right) - \left( \frac{dS_2}{dP} \right) \theta L_2 \\ &= \frac{64H_2 f_1^2}{EA_2 n_1^2} \left( h - \frac{h_1}{2} - \frac{2}{3} f_1 \right) - 8\theta \frac{f_1}{L_1} \left( h - \frac{h_1}{2} - \frac{2}{3} f_1 \right) \end{aligned}$$

(四) 塔ノ内働ト其ノ微係數

左ノ塔ニ於ケル應力ハ次ノ如シ

$$S = H_1 \frac{4f}{l} + (H_1 + P) \frac{h_1 + 4f_1}{L_1} \quad \frac{dS}{dP} = \frac{h_1 + 4f_1}{L_1}$$

$$\begin{aligned} \frac{d\omega}{dP} &= \frac{Sh_2}{EA_3} \left( \frac{dS}{dP} \right) + \frac{dS}{dP} \theta h_2 \\ &= \frac{H_1 h_2}{EA_3} \left( \frac{4f}{l} + \frac{h_1 + 4f_1}{L_1} \right) \left( \frac{h_1 + 4f_1}{L_1} \right) + \theta \frac{h_2}{L_1} \frac{h_1 + 4f_1}{L_1} \end{aligned}$$

(五) 支鞍ノ水平移動ノ決定

今温度ノ爲メニ起ル支鞍ノ水平移動ヲ  $\Delta l_1$  トスルハ次ノ如シ

$$\begin{aligned} \Delta l_1 &= \frac{H_2}{E} \left[ \frac{8f_1^2 h_1}{15L_1} + \frac{1}{4} \left( l_1 + l_2 + \frac{3h_1^2 + 16f_1^2}{2L_1} \right) \right. \\ &\quad \left. + \frac{64f_1^2}{A_2 n_1^2 L_1^2} \left( h - \frac{h_1}{2} - \frac{2}{3} f_1 \right) + \frac{h_2}{A_3} \left( \frac{4f}{l} + \frac{h_1 + 4f_1}{L_1} \right) \left( \frac{h_1 + 4f_1}{L_1} \right) \right] \\ &\quad - \theta l_1 \left( l_1 + l_2 + \frac{3h_1^2 + 16f_1^2}{3L_1} \right) + \frac{8f_1}{L_1} \left( h - \frac{h_1}{2} - \frac{2}{3} f_1 \right) - \left( \frac{h_1 + 4f_1}{L_1} \right) h_2 \dots \dots (44) \end{aligned}$$

吊材及塔ノ影響ヲ省略スルトキハ

$$dL_0 = \frac{H_0}{E} \left[ \frac{8f^2 L_0}{15L} + \frac{1}{A} \left( l_1 + l_2 + \frac{3l_1^2 + 16f^2 l_1}{2L} \right) \right] - \theta \left( l_1 + l_2 + \frac{3l_1^2 + 16f^2 l_1}{3L} \right) \dots \dots \dots (45)$$

第十二章 死荷重ノ爲メニ受クル鍊條ノ撓度

鍊條ハ其ノ初メ架設中ニアツテハ只タ自己ノ重量ヲ受クルノミナレトモ築造完了ノ後ニハ床構並ニ扶構等ヨリ來タル死荷重ノ爲メ可ナリ大ナル張力ヲ受ケ從ツテ幾等カノ撓度ヲ起スモノナリ故ニ鍊條架設ノ初メニ當ツテハ鍊條ノ中央部ヲシテ其ノ最後ノ位置ヨリモ少シク高ク置カシムルコト必要ナリ

今床構並ニ扶構等但シ鍊條ノ自重ハ含マスヨリ來ル水平毎呎ノ死荷重ヲ中央徑間及側徑間ニテ $w$ 及 $w_1$ トシ又是等ノ死荷重ヲ受ケシ後ノ最後ノ垂矢ヲ中央徑間及側徑間ニテ $f$ 及 $f_1$ トス

鍊條ハ自重ノ爲メ垂曲線(Catenary curve)ヲナスモノナレトモ床構及扶構等ヨリ來タル死荷重ヲ受クル時ハ拋線トナリ從ツテ自重ノ爲メニ生セル鍊條應力ニモ多少ノ變化ヲ生ス然レトモ其ノ差餘リ大ナラサルヲ以テ鍊條ノ自重ノ爲メニ生セル鍊條應力ニハ前後變化ナキモノト假定ス

(第一)中央鍊條ノ撓度

(A) 第一解法

今中央鍊條ニ水平毎呎 $w$ ナル死荷重ヲ掛ケ又鍊條ノ中點ニ補助荷重 $P$ ヲ掛クレハ鍊條ノ水平分力 $H$ ハ次ノ如シ

$$H = \frac{wf^2}{8f} + \frac{Pl}{4f} \qquad \frac{dH}{dP} = \frac{l}{4f}$$

$$T = H \left[ 1 + \left( \frac{8f}{l} \right)^2 \right]^{\frac{1}{2}} \qquad \frac{dT}{dH} = \left[ 1 + \left( \frac{8f}{l} \right)^2 \right]^{\frac{1}{2}}$$

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10ナル死荷重ヲ受ケサル以前ニ於テハ垂曲線ヲナスモノナレトモ之ヲ拋線ナリト假定スレハ極小曲線長  $ds$  ハ次ノ如シ

$$ds = \left[ 1 + \left( \frac{8f - 8df}{l} \right)^2 x^2 \right]^{\frac{1}{2}} dx = \left[ 1 + \left( \frac{8f}{l} \right)^2 x^2 \right]^{\frac{1}{2}} dx \quad \text{nearly}$$

第 二 Castigliano ノ第一定理ニヨリ撓度  $4f$  ハ次ノ如シ

$$\Delta f = \frac{dU}{dP} = 2 \int_0^l \frac{T}{EA} \left( \frac{dT}{dH} \right) \left( \frac{dH}{dP} \right) ds = \frac{2}{EA} \int_0^l H \left[ 1 + \left( \frac{8f}{l} \right)^2 x^2 \right]^{\frac{3}{2}} \frac{l}{4f} dx$$

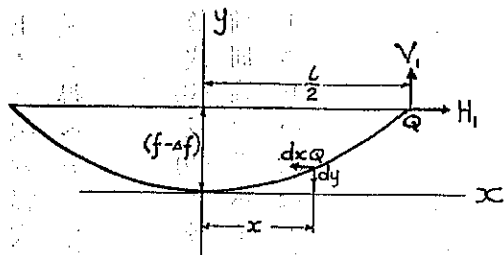
$$\begin{aligned} \therefore \Delta f &= \frac{Hl}{2EAf} \left( \frac{l}{2} + \frac{4f^2}{l} \right) \quad \text{nearly} \\ \text{OR} &= \frac{wl^3}{16EAf^3} \left( \frac{l}{2} + \frac{4f^2}{l} \right) \quad \text{nearly} \end{aligned} \quad \left. \begin{array}{l} \dots \\ \dots \\ \dots \end{array} \right\} \dots \dots (46)$$

即鍊條ノ中央部ヲシテ  $4f$  丈ケ上方ニ置カシムレハ可ナリ

(B) 第二解法

第一解法ニ於テハ原曲線 (Original curve) ヲ拋線ナリト假定シタレトモ實際ニ於テハ垂曲線ナルヲ以テ次ニ最モ正確ナル方法ヲ述ヘントス  
先ツ初メニ垂曲線ノ方程式ヲ導ケハ次ノ如シ  
今  $w'$  ヲ鍊條ノ單位長カ有スル自重トシ鍊條ノ一部分  $OO$  ノ平衡ヲ考フル下キハ容易ニ次ノ關係式ヲ得ヘシ

$$\frac{dq}{dx} = \frac{T - w' \int_0^x \sqrt{1 + \left( \frac{dq}{dx} \right)^2} dx}{H}$$



第二十四圖

$$= \frac{V_1}{H_1} - \frac{w'}{H_1} \int_a^x \sqrt{1 + \left(\frac{dy}{dx}\right)^2} dx$$

上式ヲ微分スルトキハ  $\frac{w'}{H_1} \frac{1}{2}$  等ハ常數ナルコトニ注意スルヲ要ス

$$\frac{d^2y}{dx^2} = \frac{w'}{H_1} \sqrt{1 + \left(\frac{dy}{dx}\right)^2}, \quad \frac{w'}{H_1} = c, \quad \frac{dy}{dx} = Z \text{ 置ケルハ } \frac{d^2y}{dx^2} = \frac{dZ}{dx} \text{ ナルヲ以テ}$$

$$\frac{dZ}{dx} = c \sqrt{1 + Z^2}$$

$$\int \frac{dZ}{\sqrt{1 + Z^2}} = c \int dx + C_1$$

$$\log(Z + \sqrt{1 + Z^2}) = cx + C_1$$

$$x=0 \text{ ナルトキ } \frac{dy}{dx} = Z=0 \text{ ナルハ } C_1=0 \text{ ナリ}$$

$$Z + \sqrt{1 + Z^2} = e^{cx} \quad \sqrt{1 + \left(\frac{dy}{dx}\right)^2} = e^{cx} - \frac{dy}{dx}$$

兩邊ヲ自乘シ簡單ニスレバ

$$\frac{dy}{dx} = \frac{1}{2} (e^{cx} - e^{-cx}) \quad y = \frac{1}{2} \left( \frac{1}{c} e^{cx} + \frac{1}{c} e^{-cx} \right) + C_2$$

$$x=0 \text{ ナルトキ } y=0 \text{ ナルヲ以テ } C_2 = -\frac{1}{c} \text{ ナリ}$$

$$\therefore y = \frac{1}{2c} (e^{cx} + e^{-cx} - 2) \dots \dots \dots (47)$$

$$\text{又 } s = \frac{l}{2} \text{ ノトキ } s = (f - af) \text{ ナルヲ以テ}$$

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$$\begin{aligned} (f - \Delta f) &= \frac{1}{2c} \left( e^{\frac{c^2}{2}} + e^{-\frac{c^2}{2}} - 2 \right) \\ &= \frac{1}{2c} \left( \frac{c^2}{4} + \frac{c^4}{8 \times 24} + \dots \right) \\ &= \frac{c^2}{8} + \frac{c^4}{384} \quad \text{nearby} \end{aligned}$$

上ノ三次方程式ヲ解キテ $c$ ノ値ヲ見出シ得ヘク或ハ $c$ ナル項ヲ省略スルトキハ次ノ如キ $c$ ノ略値ヲ得ヘシ

$$c = \frac{8(f - \Delta f)}{l} \dots \dots \dots (49)$$

算式(48)及(49)ニ於テ $l$ ノ値ハ初メニ之ヲ假定シ試算スルコトヲ要ス  
前同様 $w$ ヲ水平毎呎ノ死荷重トシ $P$ ヲ鏢條ノ中點ニ於ケル補助荷重トシ又 $H$ ヲ鏢條ノ水平分力トスレハ最後ノ曲線カ $f$ ナル垂矢ヲ有スル拋線ナルヲ以テ

$$H = \frac{wl^2}{8f} + \frac{Pl}{4f} \quad \frac{dH}{dP} = \frac{l}{4f}$$

$$T = H \left\{ 1 + \left( \frac{8f}{l^2} \right)^2 a^2 \right\}^{\frac{1}{2}} \quad \frac{dT}{dH} = \left\{ 1 + \left( \frac{8f}{l^2} \right)^2 a^2 \right\}^{\frac{1}{2}}$$

又原曲線ナル垂曲線ノ極小曲線長 $ds$ ハ次ノ如シ

$$ds = \sqrt{1 + \left( \frac{dy}{dx} \right)^2} dx = \frac{1}{2} (e^{ax} + e^{-ax}) dx$$



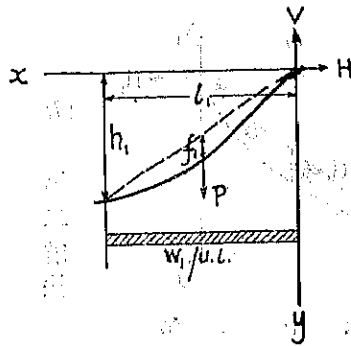


圖 五 十 二 第

止ノ式ニ於テeノ値ハ算式(48)或ハ(49)ヲ以テ計算シ得ヘク從ツテ4fノ値ヲ求メ得ルナリ  
 算式(46)ト(50)ハ殆ト同値ヲ與フルカ故ニ原曲線ヲ拋線ト假定スルモ大差ナシ  
 (第二側錄條ノ撓度)

$$df = \frac{d\omega}{dP} = 2 \int_0^{\frac{l}{2}} \frac{T}{EA} \left( \frac{dT}{dH} \right) \left( \frac{dH}{dP} \right) ds$$

$$= \frac{2}{EA} \int_0^{\frac{l}{2}} H \left\{ 1 + \left( \frac{8f}{l^2} \right) x^2 \right\} \frac{l}{4f} \frac{1}{2} (e^{ax} + e^{-ax}) dx$$

$$\therefore df = \frac{Hl}{4EAfc} \left[ \frac{e^{\frac{a}{2}} - e^{-\frac{a}{2}}}{\frac{a}{2}} + \left( \frac{8f}{l^2} \right)^2 \left\{ \frac{e^{\frac{a}{4}} \left( \frac{l^2}{4} - l + \frac{2}{c^2} \right) - e^{-\frac{a}{4}} \left( \frac{l^2}{4} + l + \frac{2}{c^2} \right) \right\} \right] \dots \dots (50)$$

(A) 第一解法

原曲線ヲ拋線ト假定シw1ヲ水平毎呎ノ死荷重トシPヲ錄條ノ中點ニ於ケル補助荷重トス

$$H = \frac{w_1 l^2}{8f} + \frac{Pl}{4f}$$

$$\frac{dH}{dP} = \frac{l}{4f}$$

$$T_1 = H \left\{ 1 + \left( \frac{h_1 + 4f}{l} - \frac{8f}{l^2} x \right)^2 \right\}^{\frac{3}{2}}$$

$$\frac{dT_1}{dH} = \left\{ 1 + \left( \frac{h_1 + 4f}{l} - \frac{8f}{l^2} x \right)^2 \right\}^{\frac{3}{2}}$$

$$T_2 = H \left\{ 1 + \left( \frac{h_1 - 4f}{l} \right)^2 \right\}^{\frac{3}{2}}$$

$$\frac{dT_2}{dH} = \left\{ 1 + \left( \frac{h_1 - 4f}{l} \right)^2 \right\}^{\frac{3}{2}}$$

$$ds = \left\{ 1 + \left( \frac{h_1 + 4f}{l} - \frac{8f}{l^2} x \right)^2 \right\}^{\frac{1}{2}} dx$$

nearby

論 說 三徑間ニシテ單扶橋ヲ有スル吊橋ノ略理論

(B) 第二解法

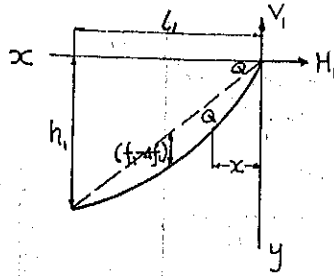


圖 六 十 二 第

原曲線ハ垂曲線ナルヲ以テ最モ正確ナル算式ヲ得ルニハ内働ノ計算ニ於テdsハ垂曲線ノ方程式ニ依ラサルヘカラス然レトモ普通ノ設計ニ於テハ第一解法ヲ以テ充分ナリトスレトモ只タ參考ノ爲メ(實際ハ不必要ナレトモ)垂曲線ノdsヲ以テ計算スレハ次ノ如シ  
先ツ初メニ垂曲線ノ方程式ヲ導カンカ爲メ第二十六圖ノ左端ニテ彎曲率ヲ取レンハ

$$T_1 = \frac{H_1 h_1 + w \int_0^{l_1} \sqrt{1 + \left(\frac{dy}{dx}\right)^2} (l_1 - x) dx}{l_1}$$

今〇〇ナル鍊條ノ平衡ヲ考フレンハ

$$\frac{dy}{dx} = \frac{T_1 - w \int_0^x \sqrt{1 + \left(\frac{dy}{dx}\right)^2} dx}{H_1}$$

$$= \frac{H_1 h_1}{l_1} + \frac{w \int_0^{l_1} \sqrt{1 + \left(\frac{dy}{dx}\right)^2} (l_1 - x) dx - w \int_0^x \sqrt{1 + \left(\frac{dy}{dx}\right)^2} dx}{H_1} \quad (51)$$

ヒテヲ後トスルハ

$$\frac{d^2y}{dx^2} = -\frac{y'}{H_1} \sqrt{1 + \left(\frac{dy}{dx}\right)^2}$$

$$\text{今 } \frac{y'}{H_1} = c, \quad \frac{dy}{dx} = Z \text{ と置くと } \frac{d^2y}{dx^2} = \frac{dZ}{dx} \text{ となる。}$$

$$\frac{dZ}{dx} = -c\sqrt{1+Z^2} \quad \log(Z + \sqrt{1+Z^2}) = -cx + C_1$$

$C_1$  は或る常数トス

$$Z + \sqrt{1+Z^2} = e^{-cx+C_1} = e^{C_1} e^{-cx}$$

$$\frac{dy}{dx} = \frac{1}{2} \left( e^{C_1} e^{-cx} - e^{-C_1} e^{cx} \right)$$

$$y = \frac{1}{2c} \left( -e^{C_1} e^{-cx} - e^{-C_1} e^{cx} \right) + C_2$$

$x=0$  ナルトキ  $y=0$  ナルヲ以テ  $C_2 = \frac{1}{2c} (e^{C_1} + e^{-C_1})$  となる。

$$\therefore y = \frac{1}{2c} \left( e^{C_1} + e^{-C_1} - e^{-C_1} e^{cx} - e^{C_1} e^{-cx} \right) \dots \dots \dots (52)$$

$x=l_1$  ナルトキ  $y=h_1$  ナルヲ以テ  $x=\frac{l_1}{2}$  となる。  $y = \frac{h_1}{2} + (F_1 - \Delta F)$  となる。

$$h_1 = \frac{1}{2c} \left( e^{C_1} + e^{-C_1} - e^{-C_1} e^{c \frac{l_1}{2}} - e^{C_1} e^{-c \frac{l_1}{2}} \right)$$

$$\frac{h_1}{2} + (F_1 - \Delta F) = \frac{1}{2c} \left\{ e^{C_1} + e^{-C_1} - e^{-C_1} e^{c \frac{l_1}{2}} - e^{C_1} e^{-c \frac{l_1}{2}} \right\}$$

上ノ二式ヨリ理論上  $O_1$  及  $e$  ノ値ヲ求メ得ルモノナレトモ  $O_1$  及  $e$  ノ略値ヲ求ムレハ次ノ如シ

$$h_1 = \frac{1}{2}(2OL_1 - d_1^2)$$

$$\frac{h_1}{2} + (f_1 - 4f_1) = \frac{1}{2} \left( OL_1 - \frac{1}{4} d_1^2 \right)$$

$$\therefore e = \frac{8(f_1 - 4f_1)}{l_1^2}$$

$$O_1 = \frac{h_1 + 4(f_1 - 4f_1)}{l_1}$$

..... (53)

前同様  $w_1$  ヲ水平毎呎ノ死荷重トシ  $P$  ヲ鍊條ノ中點ニ於ケル補助荷重トシ又  $H$  ヲ是等ノ荷重ヨリ起ル鍊條ノ水平分力トスルニ最後ノ曲線カ  $f_1$  ナル垂矢ヲ有スル拋線ナルヲ以テ

$$H = \frac{w_1 l_1^2}{8f_1} + \frac{P l_1}{4f_1}$$

$$\frac{dH}{dP} = \frac{l_1}{4f_1}$$

$$T_1 = H \left\{ 1 + \left( \frac{h_1 + 4f_1}{l_1} - \frac{8f_1 e}{l_1^2} \right)^2 \right\}^{\frac{1}{2}} \quad \frac{dT_1}{dH} = \left\{ 1 + \left( \frac{h_1 + 4f_1}{l_1} - \frac{8f_1 e}{l_1^2} \right)^2 \right\}^{\frac{1}{2}}$$

$$T_2 = H \left\{ 1 + \left( \frac{h_1 - 4f_1}{l_1} \right)^2 \right\}^{\frac{1}{2}} \quad \frac{dT_2}{dH} = \left\{ 1 + \left( \frac{h_1 - 4f_1}{l_1} \right)^2 \right\}^{\frac{1}{2}}$$

$$ds = \sqrt{1 + \left( \frac{dy}{dx} \right)^2} dx = \frac{1}{2} \left( e^{-\theta_1} e^{ax} + e^{\theta_1} e^{-ax} \right) dx$$

$$df_1 = \frac{dw}{dP} = \int_0^{l_1} \frac{T_1}{EA} \left( \frac{dT_1}{dH} \right) \left( \frac{dH}{dP} \right) ds + \frac{T_2}{EA} \left( \frac{dT_2}{dH} \right) \left( \frac{dH}{dP} \right) l_1$$

$$= \frac{H l_1}{8w_1 f_1^2} \int_0^{l_1} \left\{ 1 + \left( \frac{h_1 + 4f_1}{l_1} - \frac{8f_1 e}{l_1^2} \right)^2 \right\} \left( e^{-\theta_1} e^{ax} + e^{\theta_1} e^{-ax} \right) dx + \frac{H l_1}{EA} \left\{ 1 + \left( \frac{h_1 - 4f_1}{l_1} \right)^2 \right\} l_1$$

$$\begin{aligned} \therefore \Delta f_1 = & \frac{Hl_1}{8EAfc} \left[ \left\{ 1 + \left( \frac{h_1 + 4f_1}{l_1} \right)^2 \right\} \left\{ e^{-\alpha_1} (e^{\alpha_1} - 1) - e^{\alpha_1} (e^{-\alpha_1} - 1) \right\} \right. \\ & - \frac{16f_1(h_1 + 4f_1)}{l_1^3} \left\{ l_1 \left( e^{-\alpha_1} e^{\alpha_1} - e^{\alpha_1} e^{-\alpha_1} \right) - \frac{1}{c} \left( e^{-\alpha_1} e^{\alpha_1} + e^{\alpha_1} e^{-\alpha_1} - e^{-\alpha_1} - e^{\alpha_1} \right) \right\} \\ & + \left( \frac{8f_1}{l_1^2} \right)^2 \left\{ e^{-\alpha_1} e^{\alpha_1} \left( l_1^2 - \frac{2l_1}{c} + \frac{2}{c^2} \right) - e^{\alpha_1} e^{-\alpha_1} \left( l_1^2 + \frac{2l_1}{c} + \frac{2}{c^2} \right) \right\} \\ & \left. + \frac{2}{c^2} \left( e^{\alpha_1} - e^{-\alpha_1} \right) \right] + 2l_1 c \left[ 1 + \left( \frac{h_1 - 4f_1}{l_1} \right)^2 \right] \dots \dots \dots (54) \end{aligned}$$

$C_1$  及  $c$  ノ値ハ算式 (53) ヲ以テ之ヲ求メ得可ク從ツテ  $\Delta f_1$  ノ値ヲ計算シ得ルナリ然レトモ此ノ第二解法ハ全ク徒勞ニシテ第一解法ヲ以テ充分ナリトス(完)